

# Path Objects

## Introduction

A **Path** object manages coordinated multi-axis motion profiles. It is used when the motion profiles in an N-Dimensional space are required to follow a specific coordinated trajectory. Motion paths are constructed with high level linear and arc segments and downloaded to the controller. The controller calculates the real-time individual axis profiles.

Generally, Path motion is used when the trajectory through space is more important than the final target position. Several different algorithms can be applied to convert the linear and arc segment path into an interpolated trajectory.

Path trajectory generation is now supported by PT, PVT, SPLINE, BESSEL, BSPLINE, and BSPLINE2 algorithms. Blending of the corners is only available for the 2 bspline algorithms. Blending of a corner is when the path does not hit the corner but goes through a smooth arc.

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# mpiPathCreate

## Declaration

```
MPIPath mpiPathCreate( ) ;
```

**Required Header:** stdmpi.h

## Description

**mpiPathCreate** creates a Path object.

### Return Values

<b>handle</b>	to a Path object
<b>MPIHandleVOID</b>	if the object could not be created

## See Also

[mpiPathDelete](#) | [mpiPathValidate](#)

# mpiPathDelete

## Declaration

```
long mpiPathDelete(MPIPath path);
```

**Required Header:** stdmpi.h

## Description

**mpiPathDelete** deletes a Path object and invalidates its handle (*path*). PathDelete is the equivalent of a C++ destructor.

### Return Values

[MPIMessageOK](#)

## See Also

[mpiPathCreate](#) | [mpiPathValidate](#)

# mpiPathValidate

## Declaration

```
long mpiPathValidate(MPIPath path);
```

**Required Header:** stdmpi.h

## Description

**mpiPathValidate** validates the Path object and its handle (***command***).

### Return Values

[MPIMessageOK](#)

## See Also

[mpiPathCreate](#) | [mpiPathDelete](#)

# mpiPathParamsGet

## Declaration

```
long mpiPathParamsGet(MPIPath      path,
                     MPIPathParams *params,
                     void          *external),
```

**Required Header:** stdmpi.h

## Description

**mpiPathParamsGet** reads the parameters for a path object and writes them into the structure pointed to by *params*, and also writes it into the implementation-specific structure pointed to by *external* (if *external* is not NULL).

<b>path</b>	a handle to a Path object
<b>*params</b>	a pointer to a MPIPathParams structure
<b>*external</b>	a pointer to a void or NULL

### Return Values

[MPIMessageOK](#)

## See Also

[mpiPathParamsSet](#)

# mpiPathParamsSet

## Declaration

```
long mpiPathParamsSet(MPIPath path,
                     MPIPathParams *params,
                     void *external),
```

**Required Header:** stdmpi.h

## Description

**mpiPathParamsSet** writes the parameters from the structure pointed to by *params* into the Path object. Also, it writes the implementation-specific structure pointed to by *external* (if *external* is not NULL) into the Path.

<b>path</b>	a handle to a Path object
<b>*params</b>	a pointer to a MPIPathParams structure
<b>*external</b>	a pointer to a void or NULL

## Return Values

[MPIMessageOK](#)

## See Also

[mpiPathParamsGet](#)

# mpiPathAppend

## Declaration

```
long mpiPathAppend(MPIPath path,  
                  MPIPathElement *element);
```

Required Header: stdmpi.h

## Description

**mpiPathAppend** adds an array of path elements pointed to by *element* to the end of the *path* stored in the Path object.

### Return Values

[MPIMessageOK](#)

## See Also

[mpiPathCreate](#) | [mpiPathMotionParamsGenerate](#)



# mpiPathMotionParamsGenerate

## Declaration

```
long mpiPathMotionParamsGenerate(MPIPath path,
                                 MPIMotionParams *params);
```

**Required Header:** stdmpi.h

## Description

**mpiPathMotionParamsGenerate** calculates a list of points from the path object and writes them into the motion params structure pointed to by params. After the motion params are generated, they can be passed to [mpiMotionStart\(...\)](#). Path generated params are supported with the following motion types:

- MPIMotionTypePT
- MPIMotionTypePTF
- MPIMotionTypePVT
- MPIMotionTypePVTF
- MPIMotionTypeSPLINE
- MPIMotionTypeBESSEL
- MPIMotionTypeBSPLINE
- MPIMotionTypeBSPLINE2

To create a path, use [mpiPathCreate\(...\)](#) to create a path object. Initialize the path parameters with [mpiPathParamsGet\(...\)](#) / [mpiPathParamsSet\(...\)](#). Then add path elements (line, arc, etc.) with [mpiPathAppend\(...\)](#). Before calling [mpiPathMotionParamsGenerate\(...\)](#) make sure to specify the [MPIMotionPoint{...}](#) values in the [MPIMotionParams](#) structure. It is very important to set point.final = TRUE or FALSE before calling [mpiPathMotionParamsGenerate\(...\)](#).

<b>path</b>	a handle to a Path object
<b>*params</b>	a pointer to a <a href="#">MPIMotionParams</a> structure.

### Return Values

[MPIMessageOK](#)

## See Also

[mpiPathCreate](#) | [mpiPathParamsGet](#) | [mpiPathParamsSet](#) | [mpiPathAppend](#) | [mpiMotionStart](#)

# MPIPathArc

## Definition

```
typedef struct MPIPathArc {
    struct {
        double start;
        double included;
    } angle;
    double radius;
} MPIPathArc;
```

## Description

**MPIPathArc** specifies the parameters for an arc path element. It supports 2 dimensional arcs only. All arcs start at the end position for the last path element added to the path or the present command position if the arc is the first element in the path.

<b>start</b>	This value defines the arc's starting angle. Units are in degrees.
<b>included</b>	This value defines the relative travel angle. Units are in degrees. Positive values specify counter-clockwise motion and negative values specify clockwise motion.
<b>radius</b>	This value defines the distance from the center to the arc edge. Units are in counts.

## See Also

[MPIPathElement](#) | [MPIPathParams](#) | [MPIPathArcCenter](#)

[mpiPathAppend](#)

# MPIPathArcCenter

## Definition

```
typedef struct MPIPathArcCenter {  
    MPIPathPoint    center;  
    double          angle;  
} MPIPathArcCenter;
```

## Description

**MPIPathArcCenter** specifies the parameters for an arc path element. It supports 2 dimensional arcs only. All arcs start at the end position for the last path element added to the path or the present command position if the arc is the first element in the path.

<b>center</b>	This structure defines the coordinates for the center point of the arc. Please see <a href="#">MPIPathPoint</a> data type documentation for more information.
<b>angle</b>	This value defines the relative travel angle. Units are in degrees. Positive values specify counter-clockwise motion and negative values specify clockwise motion.

## See Also

[MPIPathElement](#) | [MPIPathParams](#) | [MPIPathArc](#)

# MPIPathArcEndPoint

## Definition

```
typedef struct MPIPathArcEndPoint {  
    MPIPathPoint    center;  
    MPIPathPoint    endPoint;  
    MPIPathDirection direction;  
} MPIPathArcEndPoint;
```

## Description

**MPIPathArcEndPoint** specifies the parameters for an arc path element. It supports 2 dimensional arcs only. All arcs start at the end position for the last path element added to the path or the present command position if the arc is the first element in the path.

<b>center</b>	This structure defines the coordinates for the center point of the arc. Please see <a href="#">MPIPathPoint</a> data type documentation for more information.
<b>endPoint</b>	This structure defines the coordinates for the final point of the arc. Please see <a href="#">MPIPathPoint</a> data type documentation for more information.
<b>direction</b>	This value defines the travel direction, counter-clockwise or clockwise. Please see <a href="#">MPIPathDirection</a> data type documentation for more information.

## See Also

[MPIPathElement](#) | [MPIPathParams](#) | [MPIPathDirection](#)

# MPIPathAttr

## Definition

```
typedef enum {  
    MPIPathElementAttrINVALID      = -1,  
    MPIPathElementAttrRELATIVE     = MPIPathElementAttrLAST - 1,  
    MPIPathElementAttrID           = MPIPathElementAttrLAST - 2,  
    MPIPathElementAttrVELOCITY     = MPIPathElementAttrLAST - 3,  
    MPIPathElementAttrACCEL        = MPIPathElementAttrLAST - 4,  
    MPIPathElementAttrTIMESLICE    = MPIPathElementAttrLAST - 5,  
    MPIPathElementAttrCOUNT       = MPIPathElementAttrLAST - MPIPathElementAttrFIRST,  
} MPIPathAttr;
```

## Description

In **MPIPathAttr**, the path attributes are used to generate the path attribute masks to enable features with `mpiPathAppend(...)`. Please see [MPIPathElementAttrMask](#) data type for more information.

## See Also

[mpiPathAppend](#)

# MPIPathDirection

## Definition

```
typedef enum {  
    MPIPathDirectionCW = -1,  
    MPIPathDirectionCCW = 1,  
} MPIPathDirection;
```

## Description

<b>MPIPathDirectionCW</b>	This value defines the clockwise direction.
<b>MPIPathDirectionCCW</b>	This value defines the counter-clockwise direction.

## See Also

[MPIPathArcEndPoint](#)

# MPIPathElement

## Definition

```
typedef struct MPIPathElement {
    MPIPathElementType    type;
    long                  blending;
    union {
        MPIPathArc        arc;
        MPIPathArcCenter  arcCenter;
        MPIPathArcEndPoint arcEndPoint;
        MPIPathLine       line;
    } params;

    MPIPathElementAttributes attributes;
} MPIPathElement;
```

## Description

<b>type</b>	This value defines the type of path element. Please see <a href="#">MPIPathElementType</a> data type documentation for more information.
<b>blending</b>	This value determines whether the corners of the path are rounded or sharp. When set to TRUE, blending is enabled, causing rounded corners. When set to FALSE, blending is disabled, causing sharp corners.
<b>arc</b>	This structure defines the arc's start angle, included angle, and radius. This structure is used when the type is MPIPathElementTypeARC. Please see <a href="#">MPIPathArc</a> data type documentation for more information.
<b>arcCenter</b>	This structure defines the arc's center and angle. This structure is used when the type is MPIPathElementTypeARC_CENTER. Please see <a href="#">MPIPathArcCenter</a> data type documentation for more information.
<b>arcEndPoint</b>	This structure defines the arc's center, end point, and direction. This structure is used when the type is MPIPathElementTypeARC_END_POINT. Please see <a href="#">MPIPathArcEndPoint</a> data type documentation for more information.
<b>line</b>	This structure defines the coordinates for a linear element. This structure is used when the type is MPIPathElementTypeLINE. Please see <a href="#">MPIPathLine</a> data type documentation for more information.
<b>attributes</b>	This structure defines the attributes for a path element. Please see <a href="#">MPIPathElementAttributes</a> data type documentation for more information.

## See Also



# MPIPathElementAttributes

## Definition

```
typedef struct MPIPathElementAttributes {
    long    id;                /* MPIPathAttrID          */
    double  velocity;          /* MPIPathAttrVELOCITY    */
    double  acceleration;      /* MPIPathAttrACCELERATION */
    double  timeSlice;        /* MPIPathAttrTIMESLICE   */
} MPIPathElementAttributes;
```

## Description

In **MPIPathElementAttributes**, the path attributes define the parameters to be used when specific features are enabled with the path element attribute masks. When using these attributes, be sure to enable the feature with the appropriate **MPIPathElementAttrMask{.}**.

<b>id</b>	This value defines an identification number to be stored in the path element. During path profile execution, at the start of each element the controller loads the id into the axis' ElementID field. The application can query the controller's axis memory to monitor the path element execution. The id is limited to 16-bit resolution by the controller firmware.
<b>velocity</b>	This value defines the velocity for the path element.
<b>acceleration</b>	This value defines the acceleration for the path element.
<b>timeSlice</b>	This value defines the time between interpolation points for the path element. The practical range for the time slice is from 10 msec (.01) to 100 msec (.1). Larger time slice values produce smoother (lower acceleration), less accurate paths. Smaller time slice values produce more accurate (both position and velocity) paths with higher peak accelerations.

## See Also

[MPIPathElementAttrMask](#)

# MPIPathElementAttrMask

## Definition

```
typedef enum {
    MPIPathElementAttrMaskRELATIVE,
        = mpiPathElementAttrMaskBIT(MPIPathElementAttrRELATIVE),
    MPIPathElementAttrMaskID,
        = mpiPathElementAttrMaskBIT(MPIPathElementAttrID),
    MPIPathElementAttrMaskVELOCITY,
        = mpiPathElementAttrMaskBIT(MPIPathElementAttrVELOCITY),
    MPIPathElementAttrMaskACCEL,
        = mpiPathElementAttrMaskBIT(MPIPathElementAttrACCEL),
    MPIPathElementAttrMaskTIMESLICE,
        = mpiPathElementAttrMaskBIT(MPIPathElementAttrTIMESLICE),

    MPIPathElementAttrMaskALL    = -1 << MPIPathElementAttrFIRST,
} MPIPathElementAttrMask;
```

## Description

In **MPIPathElementAttrMask**, the path attribute masks are used to enable features with `mpiPathAppend(...)`. The masks are ORed with the `MPIPathElementType` to enable each feature.

<b>MPIPathElementAttrMaskRELATIVE</b>	This mask enables relative coordinates for path motion. <b>This feature is not supported and is reserved for future use.</b>
<b>MPIPathElementAttrMaskID</b>	This mask enables an identification tag to be stored in the path. Each element can have a unique identification. Please see <a href="#">MPIPathElementAttributes</a> data type documentation for more information.
<b>MPIPathElementAttrMaskVELOCITY</b>	This mask enables a path velocity to be specified for each element. Please see <a href="#">MPIPathElementAttributes</a> data type documentation for more information.
<b>MPIPathElementAttrMaskACCEL</b>	This mask enables a path acceleration to be specified for each element. Please see <a href="#">MPIPathElementAttributes</a> data type documentation for more information.
<b>MPIPathElementAttrMaskTIMESLICE</b>	This mask enables a path time slice to be specified for each element. Please see <a href="#">MPIPathElementAttributes</a> data type documentation for more information.

## See Also

[MPIPathElementType](#) | [mpiPathAppend](#)

# MPIPathElementType

## Definition

```
typedef enum {
    MPIPathElementTypeINVALID,
    MPIPathElementTypeARC,           /* only 2D */
    MPIPathElementTypeARC_CENTER,   /* only 2D */
    MPIPathElementTypeARC_END_POINT, /* both 2D and 3D */
    MPIPathElementTypeHELIX,         /* not currently supported */
    MPIPathElementTypeIO,           /* not currently supported */
    MPIPathElementTypeLINE,        /* both 2D and 3D */

    MPIPathElementTypeMASK,
} MPIPathElementType;
```

## Description

<b>MPIPathElementTypeARC</b>	This type generates an arc specified by the arc's start angle, included angle, and radius.
<b>MPIPathElementTypeARC_CENTER</b>	This type generates an arc specified by the arc's center and angle.
<b>MPIPathElementTypeARC_END_POINT</b>	This type generates an arc specified by the arc's center, end point, and direction.
<b>MPIPathElementTypeLINE</b>	This type generates a line specified by the position coordinates.

## See Also

[MPIPathArc](#) | [MPIPathLine](#)

# MPIPathLine

## Definition

```
typedef struct MPIPathLine {  
    MPIPathPoint    point;  
} MPIPathLine;
```

## Description

**MPIPathLine** specifies the parameters for a linear path element. It supports up to MPIPathPointDIMENSION\_MAX dimensions. All lines start at the end position for the last path element added to the path or the present command position if the line is the first element in the path.

<b>point</b>	This structure defines the end point coordinates for the linear segment.
--------------	--

## See Also

[MPIPathElement](#) | [MPIPathParams](#) | [MPIPathPointDIMENSION\\_MAX](#)

# MPIPathMessage

## Definition

```
typedef enum {  
    MPIPathMessagePATH_INVALID,  
    MPIPathMessageILLEGAL_DIMENSION,  
    MPIPathMessageILLEGAL_ELEMENT,  
    MPIPathMessageARC_ILLEGAL_DIMENSION,  
    MPIPathMessageHELIX_ILLEGAL_DIMENSION,  
    MPIPathMessageILLEGAL_RADIUS,  
    MPIPathMessagePATH_TOO_LONG,  
    MPIPathMessageILLEGAL_VELOCITY,  
    MPIPathMessageILLEGAL_ACCELERATION,  
    MPIPathMessageILLEGAL_TIMESLICE,  
    MPIPathMessageINVALID_BLENDING,  
} MPIPathMessage;
```

## Description

**MPIPathMessage** is an enumeration of the Path error messages that can be returned by the MPI library.

### MPIPathMessagePATH\_INVALID

The path object is not valid. This message code is returned by a path method if the path object handle is not valid. This problem can be caused by a failed [mpiPathCreate\(...\)](#). To prevent this problem, check your path objects after creation by using [mpiPathValidate\(...\)](#).

### MPIPathMessageILLEGAL\_DIMENSION

The path dimensions are not valid. This message code is returned by [mpiPathParamsSet\(...\)](#) or [mpiPathMotionParamsGenerate\(...\)](#) if the path dimension is less than one or greater than or equal to `MPIPathPointDIMENSION_MAX`. Also, this message code is returned if specific path element types have dimension restrictions. For example, the `ARC` type is limited to 2 dimensions and the `ARC_END_POINT` type is limited to 3 dimensions. To correct this problem, select an appropriate dimension for the path element type.

### MPIPathMessageILLEGAL\_ELEMENT

The path element type is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the specified path element type is not a member of the [MPIPathElementType](#) enumeration.

### MPIPathMessageARC\_ILLEGAL\_DIMENSION

The path element arc dimension is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the ARC or ARC\_CENTER element is not 2 dimensions. To correct this problem, set the path dimension to 2.

#### **MPIPathMessageHELIX\_ILLEGAL\_DIMENSION**

Not supported.

#### **MPIPathMessageILLEGAL\_RADIUS**

The path element arc radius is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the ARC element radius is less than or equal to zero. To correct this problem, set the arc radius to a value greater than zero.

#### **MPIPathMessagePATH\_TOO\_LONG**

The path length is not valid. This message code is returned by [mpiPathMotionParamsGenerate\(...\)](#) if the path length is greater than MAX\_PATH\_POINTS. To correct the problem, specify a path with fewer points than MAX\_PATH\_POINTS.

#### **MPIPathMessageILLEGAL\_VELOCITY**

The path element velocity is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the specified velocity is less than or equal to zero. To correct this problem, set the element velocity to a value greater than zero.

#### **MPIPathMessageILLEGAL\_ACCELERATION**

The path element velocity is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the specified velocity is less than or equal to zero. To correct this problem, set the element velocity to a value greater than zero.

#### **MPIPathMessageILLEGAL\_TIMESLICE**

The path element time slice is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the specified time slice is less than or equal to zero. To correct this problem, set the element time slice to a value greater than zero.

#### **MPIPathMessageINVALID\_BLENDING**

The path element blending is not valid. This message code is returned by [mpiPathMotionParamsGenerate\(...\)](#) if the element blending is set to TRUE and the motion type does not support blending. To correct this problem, either set the element blending to FALSE or select a different motion type.

## **See Also**

# MPIPathParams

## Definition

```
typedef struct MPIPathParams {
    long          dimension;
    MPIPathPoint start;
    double        velocity;
    double        acceleration;
    double        deceleration;
    MPIMotionType interpolation;
    double        timeSlice;
    double        conversion
                [MPIPathPointDIMENSION\_MAX][MPIPathPointDIMENSION\_MAX];
} MPIPathParams;
```

## Description

<b>dimension</b>	This value defines the number of axes to coordinate. Please see <a href="#">MPIPathPoint</a> data type documentation for more information.
<b>start</b>	This structure defines the initial point for the path.
<b>velocity</b>	This value defines the speed along the path. The units are in counts per second.
<b>acceleration</b>	This value defines the rate of change of speed to reach the velocity along the path. The units are in counts per second * second.
<b>deceleration</b>	This value defines the rate of change of speed to reach zero velocity along the path. The units are in counts per second * second.
<b>interpolation</b>	This value specifies the motion algorithm to generate the path. Please see <a href="#">MPIMotionType</a> data type documentation for more information.
<b>timeSlice</b>	This value specifies the amount of time between points. The units are in seconds. Smaller timeSlice values will improve the path accuracy, but increase the number of points to calculate and buffer.



**conversion**

This value is an  $N \times N$  matrix (where  $N$  is the number of dimensions in the path motion) that scales and rotates the axes used in the path motion. This is useful when using two axes with different resolutions for each axis.

**For two axes with different resolution:**

Set conversion[0][0] to (desired x resolution / actual x resolution)

Set conversion [1][1] to (desired y resolution / actual y resolution)

Set conversion[0][1] and conversion[1][0] = 0

**For a coordinate rotation, where alpha is the rotation of the coordinate system:**

Set conversion[0][0] and conversion [1][1] = cos(alpha)

Set conversion[0][1] = sin(alpha)

Set conversion[1][0] = -sin(alpha)

**See Also**

[mpiPathParamsGet](#) | [mpiPathParamsSet](#) | [mpiPathMotionParamsGenerate](#) | [MPIPathPointDIMENSION\\_MAX](#)

# MPIPathPoint

## Definition

```
typedef struct MPIPathPoint {  
    double    position[MPIPathPointDIMENSION_MAX];  
} MPIPathPoint;
```

## Description

**position**

This array defines the axis command positions for a path point. There must be one position value for each dimension.

## See Also

[MPIPathParams](#) | [mpiPathParamsGet](#) | [mpiPathParamsSet](#) | [mpiPathPointDIMENSION\\_MAX](#)

# mpiPathElementType

## Declaration

```
#define mpiPathElementType(type) ((type) & MPIPathElementTypeMASK)
```

**Required Header:** stdmpi.h

## Description

**mpiPathElementType** is a macro that masks off all other bits in type, leaving the path element type.

## See Also

[MPIPathElementType](#)

# mpiPathElementAttrMaskBIT

## Declaration

```
#define mpiPathElementAttrMaskBIT(attr) (0x1 << (attr))
```

**Required Header:** stdmpi.h

## Description

**mpiPathElementAttrMaskBIT** is a macro that converts the path element attribute into the path element attribute mask.

## See Also

[MPIPathElementAttrs](#) | [MPIPathElementAttrMask](#)

# mpiPathElementATTR

## Declaration

```
#define mpiPathElementATTR(type,attr)
    ((type) |= mpiPathElementAttrMaskBIT\(attr\))
```

**Required Header:** stdmpi.h

## Description

**mpiPathElementATTR** is a macro that turns on the specified path element attribute mask bits in the path element type.

## See Also

[MPIPathAttr](#) | [MPIPathElementAttrMask](#)

# MPIPathPointDIMENSION\_MAX

## Definition

```
#define MPIPathPointDIMENSION_MAX (16)
```

## Description

**MPIPathPointDIMENSION\_MAX** defines the maximum dimensions for path objects.

## See Also

[MPIPathParams](#) | [mpiPathParamsGet](#) | [mpiPathParamsSet](#) | [mpiPathPointDIMENSION\\_MAX](#)

# MPIPathPointPOINTS\_MAX

## Definition

```
#define MPIPathPointPOINTS_MAX (5000)
```

## Description

**MPIPathPointPOINTS\_MAX** defines the maximum number of points for a path.

## See Also

[MPIPathParams](#) | [mpiPathMotionParamsGenerate](#)