SynqNet Objects

Introduction

A **SynqNet** object manages a single SynqNet network connected to a motion controller. It represents the physical network. It contains information about the network state, number of nodes, and netowrk status.

A SynqNet network can have one or more SqNode objects associated with it and each SqNode object can have one or more motors and/or drive interfaces. The SynqNet network provides read/write access to each node. During network initialization, the SynqNet nodes are discovered and mapped to the SynqNet object. The number of motors per SqNode object are determined and mapped to the controller's motor objects.

Methods

Create, Delete, Validate Methods

meiSynqNet**Create**

meiSynqNet**Delete**

meiSynqNet**Validate**

Configuration and Information Methods

meiSynqNet**CableNumToNodePort**

meiSynqNet**ConfigGet**

meiSynqNet**ConfigSet**

meiSynqNet**FlashConfigGet**

meiSynqNet**FlashConfigSet**

meiSynqNet**IdleCableListGet**

meiSynqNet**IdleCableStatus**

meiSynqNet**Info**

meiSynqNet**PacketFlashConfigGet**

meiSynqNet**PacketFlashConfigSet**

meiSynqNet**PortToCableNum**

meiSynqNet**PacketConfigGet**

meiSynqNet**PacketConfigSet**

meiSynqNet**Status**

meiSynqNet**Timing**

Action Methods

meiSynqNet**FlashTopologyClear**

meiSynqNet**FlashTopologySave**

meiSynqNet**Init**

meiSynqNet**Shutdown**

Event Methods

meiSynqNet**EventNotifyGet**

meiSynqNet**EventNotifySet**

meiSynqNet**EventReset**

Relational Methods

meiSynqNet**Control**

meiSynqNet**Number**

Data Types

MEISynqNet**CableList**

MEISynqNet**CableLength**

MEISynqNet**CableStatus**

MEISynqNet**Config**

MEISynqNet**FailedNodeMask**

MEISynqNet**Info**

MEISynqNet**Message**

MEISynqNet**RecoveryMode**

MEISynqNet**ResourceCommand**

MEISynqNet**ResourceIoBits**

MEISynqNet**ResourceMonitor**

MEISynqNet**PacketCfg**

MEISynqNet**PacketCfgEncoder**

MEISynqNet**PacketCfgIo**

MEISynqNet**PacketCfgMotor**

MEISynqNet**PacketCfgNode**

MEISynqNet**ResourceCfgProbe**

MEISynqNet**ResourceCfgProbeDepth**

MEISynqNet**State**

MEISynqNet**Status**

MEISynqNet**StatusCrcError**

MEISynqNet**Timing**

MEISynqNet**Trace**

Constants

MEISynqNet**MaxCableHOP_COUNT**

MEISynqNet**MaxMotorFEEDBACK_PRIMARY_COUNT**

MEISynqNet**MaxMotorFEEDBACK_SECONDARY_COUNT**

MEISynqNet**MaxMotorCAPTURE_COUNT**

MEISynqNet**MaxMotorCOMPARE_COUNT**

MEISynqNet**MaxMotorENCODER_COUNT**

MEISynqNet**MaxMotorPULSE_ENGINE_COUNT**

MEISynqNet**MaxMotors**

MEISynqNet**MaxNodeMOTORS**

MEISynqNet**MaxNODE_COUNT**

MEISynqNet**NodeMaskELEMENTS**

MEISynqNet**PacketCfgIo**

MEISynqNet**PacketCfgMotor**

MEISynqNet**PacketCfgNode**

meiSynqNetCreate

Declaration

```
meiSynqNetCreate(MPIControl  control,
                 long        number)
```

Required Header

stdmei.h

Description

SynqNetCreate creates a SynqNet object identified by ***number***, which is associated with a ***control*** object.

SynqNetCreate is the equivalent of a C++ constructor.

control	a handle to a Control object
number	An index to the SynqNet network. First network = 0 Second network = 1 Third network = 2, etc.

Return Values

handle	to a SynqNet object. After creating a SynqNet object it must be validated using meiSynqNetValidate().
MPIHandleVOID	if the object could not be created

See Also

meiSynqNetDelete | meiSynqNetValidate

meiSynqNetDelete

Declaration

```
long meiSynqNetDelete(MEISynqNet  synqNet);
```

Required Header

stdmei.h

Description

SynqNetDelete deletes a SynqNet object and invalidates its handle.

SynqNetDelete is the equivalent of a C++ constructor.

synqNet	a handle to a SynqNet object.

Remarks

All objects that are created must be deleted in the reverse order to avoid memory leaks.

Return Values

MPIMessageOK	if *SynqNetDelete* successfully deleted the object.

See Also

meiSynqNetCreate | meiSynqNetValidate

meiSynqNetValidate

Declaration

```
long meiSynqNetValidate(MEISynqNet  synqNet);
```

Required Header

stdmei.h

Description

SynqNetValidate validates the SynqNet object and its handle. SynqNetValidate should be called immediately after an object is created.

synqNet	a handle to SynqNet object

Return Values

MPIMessageOK	if SynqNet is a handle to a valid object.
MEISynqNetMessageINTERFACE_NOT_FOUND	if the controller does not support a SynqNet interface.

See Also

meiSynqNetCreate | meiSynqNetDelete

meiSynqNetCableNumToNodePort

Declaration

```
long meiSynqNetCableNumToNodePort(MEISynqNet      synqNet,
                                  long            cableNumber,
                                  long            *nodeNumber,
                                  MEINetworkPort  *port);
```

Required Header

stdmei.h

Description

SynqNetCableNumToNodePort converts a cable number on a SynqNet network into a node number and port. It reads the node number and writes it into a long pointed to by ***nodeNumber*** and reads the port and writes it to the value pointed to by ***port***.

Network connections can be identified by a cable number OR a node number and port. For simple network topologies, it is easier to identify network connections by a cable number. For complex network topologies, it is easier to identify network connections by a node number and port.

synqNet	a handle to the SynqNet object
cableNumber	the number of the cable
***nodeNumber**	a pointer to a node number
***port**	a pointer to an enumerated port value

Return Values

MPIMessageOK	if *SynqNetCableNumToNodePort* successfully converts a cable number on a SynqNet network into a node number and port.

See Also

meiSynqNetNodePortToCableNum | MEISynqNetCableList

meiSynqNetConfigGet

Declaration

```
long meiSynqNetConfigGet(MEISynqNet          synqNet,
                         MEISynqNetConfig    *config);
```

Required Header stdmei.h

Description **SynqNetConfigGet** reads a SynqNet network (***synqNet***) configuration and writes it into the structure pointed to by ***config***.

synqNet	a handle to a SynqNet object
***config**	a pointer to a SynqNet config structure.

Return Values

MPIMessageOK	if *meiSynqNetConfigGet* successfully reads a SynqNet network's configuration and writes it into the structure pointed to by *config*.

See Also meiSynqNetInfo | meiSqNodeConfigGet | meiSynqNetConfigSet

meiSynqNetConfigSet

Declaration

```
long meiSynqNetConfigSet(MEISynqNet          synqNet,
                         MEISynqNetConfig    *config);
```

Required Header stdmei.h

Description **SynqNetConfigSet** writes a SynqNet network (***synqNet***) configuration from the structure pointed to by ***config***.

synqNet	a handle to a SynqNet object
***config**	a pointer to a SynqNet config structure.

Return Values

MPIMessageOK	if *meiSynqNetConfigSet* successfully writes a SynqNet network's configuration from the structure pointed to by ***config***.
MPIMessageARG_INVALID	if config is NULL
MPIMessagePARAM_INVALID	if an invalid recoveryMode was specified or a non-zero cable length value was specified for a non-existent cable.
MPISynqNetMessageRING_ONLY	only a value of MEISynqNetRecoveryModeDISABLED for recoveryMode is allowed on a string network.

See Also meiSynqNetInfo | meiSqNodeConfigSet | meiSynqNetConfigGet

meiSynqNetFlashConfigGet

Declaration

```
long meiSynqNetFlashConfigGet(MEISynqNet          synqNet,
                              void                *flash,
                              MEISynqNetConfig    *config);
```

Required Header

stdmei.h

Description

SynqNetFlashConfigGet gets a SynqNet object's flash configuration and writes it in the structure pointed to by ***config***,.

synqNet	a handle to a SynqNet object
***config**	pointer to a locally instantiated MEISynqNetConfig structure.
***flash**	***flash*** is either an MEIFlash handle or MPIHandleVOID. If ***flash*** is MPIHandleVOID, an MEIFlash object will be created and deleted internally.

Return Values

MPIMessageOK	if *meiSynqNetIdleFlashConfigGet* successfully writes the Motor's flash configuration to the structure(s).

See Also

meiSynqNetFlashConfigSet | MEISynqNetConfig | MEIFlash

meiSynqNetFlashConfigSet

Declaration

```
long meiSynqNetFlashConfigSet(MEISynqNet        synqNet,
                              MEISynqNetConfig  *flash,
                              MEIFlash          *config);
```

Required Header

stdmei.h

Description

SynqNetFlashConfigSet gets a SynqNet object's flash configuration and writes it in the structure pointed to by ***config***.

NOTE: The network topology must first be saved before changing MEISynqNetConfig.cableLength[n] values in Flash memory. These values will also be cleared when network topology is cleared using meiSynqNetFlashTopologyClear(…).

synqNet	a handle to a SynqNet object
***config**	pointer to a locally instantiated MEISynqNetConfig structure that has been initialized by performing a call to meiSynqNetFlashConfigGet(…) or meiSynqNetConfigGet(…).
***flash**	***flash*** is either an MEIFlash handle or MPIHandleVOID. If ***flash*** is MPIHandleVOID, an MEIFlash object will be created and deleted internally. If ***flash*** is a valid MEIFlash handle, then the MEIFlash object cache will be updated but the actual write to controller flash will not occur. Use meiFlashMemoryFromFileType(...) to prompt the actual write to flash.

Return Values

MPIMessageOK	if *meiSynqNetIdleFlashConfigSet* successfully sets the Motor's flash configuration using data from the structure(s).
MPIMessageARG_INVALID	if config is NULL.
MPIMessagePARAM_INVALID	if an invalid recoveryMode was specified or a non-zero cable length value was specified for a non-existent cable.

meiSynqNetIdleCableListGet

Declaration

```
long meiSynqNetIdleCableListGet(MEISynqNet          synqNet,
                                MEISynqNetCableList *idleCable);
```

Required Header

stdmei.h

Description

SynqNetIdleLinkGet reads a SynqNet network's list of idle cables and writes them into the structure pointed to by ***idleCable***. An idle cable has no data traffic. It is the redundant network connection available in ring topologies only. A single ring topology has only one idle cable.

After network initialization, the cable from the last node to the controller is idle by default. If a network fault occurs and the network is configured for fault recovery, the network traffic will be redirected around the faulty connection, through the idle cable, and the faulty connection will become the new idle cable. To test the idle cable, use the meiSynqNetIdleCableStatus(…) method.

synqNet	a handle to a SynqNet object
***idleCable**	a pointer to a SynqNet cable list structure. The cable list structure contains the number of idle cables and their identifying numbers.

Return Values

MPIMessageOK	if *meiSynqNetIdleCableListGet* successfully reads a SynqNet network's list of idle cables and writes them into the structure pointed to by *idleCable*.

See Also

meiSynqNetIdleCableStatus | SynqNet Topologies

MEISynqNetMessageRING_ONLY	only a value of MEISynqNetRecoveryModeDISABLED for recoveryMode is allowed on a string network.
MEIFlashMessageNETWORK_TOPOLOGY_ERROR	if topology has not yet been saved to flash using meiSynqNetFlashTopologyClear(...)

See Also

MEISynqNetConfig | MEIFlash | meiSynqNetFlashConfigGet | meiSynqNetConfigGet | meiSynqNetFlashTopologySave | meiSynqNetFlashTopologyClear

meiSynqNetIdleCableStatus

Declaration

```
long meiSynqNetIdleCableStatus(MEISynqNet          synqNet,
                               long                cableNumber,
                               MEISynqNetCableStatus *cableStatus);
```

Required Header

stdmei.h

Description

SynqNetIdleCableStatus reads an idle cable's status and writes it into the structure pointed to by ***cableStatus***. Normally, the idle cable has no data traffic. SynqNetIdleCableStatus sends a special test packet across the specified idle cable and then waits for a valid response, then it sends another test packet in the opposite direction and waits for valid response.

The idle cable number for a network can be found using meiSynqNetIdleCableListGet(…). SynqNetIdleCableStatus is not allowed for non-idle cables or when the network is recovering from a fault. During fault recovery (SynqNetState = SYNQ_RECOVERING), the network traffic is redirected around the faulty connection and the idle cable is reassigned. After recovery is complete (SynqNetState = SYNQ), the new idle cable can be tested with SynqNetIdleCableStatus. Use meiSynqNetStatus(…) to determine the SynqNet state.

synqNet	a handle to a SynqNet object
cableNumber	the number of the cable to be tested
***cableStatus**	a pointer to a SynqNet cable status enumerated value.

Return Values

MPIMessageOK	if *meiSynqNetIdleCableStatus* successfully reads an idle cable's status and writes it into the structure pointed to by *cableStatus*.

See Also

meiSynqNetIdleCableListGet | MEISynqNetState

meiSynqNetInfo

Declaration

```
long meiSynqNetInfo(MEISynqNet      synqNet,
                    MEISynqNetInfo  *info);
```

Required Header

stdmei.h

Description

SynqNetInfo reads static information about the network associated with the ***SynqNet*** object and writes it into the structure pointed to by ***info***. The SynqNet info structure contains read only data that was determined during network initialization.

synqNet	a handle to a SynqNet object
***info**	pointer to a SynqNet network information structure

Return Values

MPIMessageOK	if *SynqNetInfo* successfully reads the network information and writes it into the info structure.
MPIMessageARG_INVALID	if the info pointer is NULL.

See Also

meiSynqNodeInfo | meiSynqNetStatus

meiSynqNetPacketFlashConfigGet

Declaration

```
long  meiSynqNetPacketFlashConfigGet(MEISynqNet          synqNet,
                                     void                *flash,
                                     MEISynqNetPacketCfg *config);
```

Required Header

stdmei.h

Description

SynqNetPacketFlashConfigGet is currently unsupported and is reserved for future use.

synqNet	a handle to a SynqNet object
***flash**	***flash*** is either an MEIFlash handle or MPIHandleVOID. If ***flash*** is MPIHandleVOID, an MEIFlash object will be created and deleted internally. If ***flash*** is a valid MEIFlash handle, then the MEIFlash object cache will be updated, but the actual write to controller flash will not occur. Use meiFlashMemoryFromFileType(...) to prompt the actual write to flash.
***config**	pointer to configuation structure defined by MEISynqNetPacketCfg.

Return Values

MPIMessageUNSUPPORTED	is cuurrently not supported.

See Also

meiSynqNetPacketFlashConfigSet | MEISynqNetPacketCfgNode

meiSynqNetPacketFlashConfigSet

Declaration

```
long  meiSynqNetPacketFlashConfigSet(MEISynqNet          synqNet,
                                     void                *flash,
                                     MEISynqNetPacketCfg *config);
```

Required Header

stdmei.h

Description

SynqNetPacketFlashConfigSet is currently unsupported and is reserved for future use.

synqNet	a handle to a SynqNet object
***flash**	***flash*** is either an MEIFlash handle or MPIHandleVOID. If ***flash*** is MPIHandleVOID, an MEIFlash object will be created and deleted internally. If ***flash*** is a valid MEIFlash handle, then the MEIFlash object cache will be updated but the actual write to controller flash will not occur. Use meiFlashMemoryFromFileType() to prompt the actual write to flash
***config**	pointer to configuation structure defined by MEISynqNetPacketCfg.

Return Values

MPIMessageUNSUPPORTED	currently not supported.

See Also

meiSynqNetPacketFlashConfigGet | MEISynqNetPacketCfgNode

meiSynqNetNodePortToCableNum

Declaration

```
long meiSynqNetNodePortToCableNum(MEISynqNet      synqNet,
                                  long            nodeNumber,
                                  MEINetworkPort  port,
                                  long            *cableNumber);
```

Required Header

stdmei.h

Description

SynqNetNodePortToCableNum converts a node number and port on a SynqNet network into a cable number. It reads the cable number and writes it into a long pointed to by ***cableNumber***.

Network connections can be identified by a cable number OR a node number and port. For simple network topologies, it is easier to identify network connections by a cable number. For complex network topologies, it is easier to identify network connections by a node number and port.

synqNet	a handle to the SynqNet object
nodeNumber	the number of the node
port	an enumerated port value
***cableNumber**	a pointer to a cable number

Return Values

MPIMessageOK	if *SynqNetPortToCableNum* successfully converts a node number and port on a SynqNet network into a cable number.

See Also

MEISynqNetCableList

meiSynqNetPacketConfigGet

Declaration

```
long  meiSynqNetPacketConfigGet(MEISynqNet          synqNet,
                                MEISynqNetPacketCfg *config);
```

Required Header

stdmei.h

Description

SynqNetPacketConfigGet reads the current network packet configuration for all nodes found on the network to the location pointed to by ***config***.

This method is useful for viewing the current network packed data being sent across the network. It is used in conjunction with SynqNetPacketConfigSet. This method is also useful for optimizing network traffic (bandwith).

Only configurable packet data fields are configured by this method. Fixed packet fields are not application configurable.

synqNet	a handle to a SynqNet object
***config**	pointer to configuation structure defined by MEISynqNetPacketCfg.

Return Values

MPIMessageOK	if *SynqNetPacketConfigGet* successfully reads the network packet configuration.
MPIMessageARG_INVALID	if the config pointer is NULL.
MPIMessageUNSUPPORTED	An sqNodeLib module is missing or it contains a corrupt a resource table.

See Also

meiSynqNetPacketConfigSet | MEISynqNetPacketCfgNode

meiSynqNetPacketConfigSet

Declaration

```
long  meiSynqNetPacketConfigSet(MEISynqNet           synqNet,
                                MEISynqNetPacketCfg  *config);
```

Required Header

stdmei.h

Description

SynqNetPacketConfigSet sets the network packet configuration to the configuration defined in the location pointed to by ***config***.

WARNING: meiSynqNetPacketConfigSet(...) is a low-level network routine that will clear other controller object configurations and reset the SynqNet network. This method should be executed in your application before configuring any other MPI objects.

This method is useful for optimizing network traffic (bandwith).

Only configurable packet data fields are configured by this method. Fixed packet fields are not application configurable.

synqNet	a handle to a SynqNet object
***config**	pointer to configuration structure defined by MEISynqNetPacketCfg.

Return Values

MPIMessageOK	if *SynqNetPacketConfigSet* successfully writes the network packet configuration.
MPIMessageARG_INVALID	if the config pointer is NULL.
MEISynqNetMessageINCOMPLETE_MOTOR	minimum packet requirements for a motor have not been met. Be sure that your motor has at least one command field and one encoder.
MEISynqNetMessageINVALID_AUX_ENC_COUNT	too many secondary encoders have been configured on a node, or there are more secondary encoders than configured/enabled motors.
MEISynqNetMessageINVALID_MOTOR_COUNT	more motors configured than supported by the node.
MEISynqNetMessageINVALID_COMMAND_CFG	an unsupported command value has been selected, or it is not supported by the node.
MEISynqNetMessageINVALID_ENCODER_COUNT	feedback count exceeds MEISynqNetMaxEncoderFEEDBACK_COUNT, or exceeds the count supported by the node.
MEISynqNetMessageINVALID_CAPTURE_COUNT	capture count value is out of range, capture count exceeds capture resources supported by the node, or capture count is non-zero when encoder is disabled (feedbackCount == 0x0).

meiSynqNetStatus

Declaration

```
long meiSynqNetStatus(MEISynqNet          synqNet,
                      MEISynqNetStatus    *status);
```

Required Header

stdmei.h

Description

SynqNetStatus reads status from the network associated with the SynqNet object and writes it into the structure pointed to by status. The SynqNet status structure contains network operation state and error counters. This data is updated every controller sample.

synqNet	a handle to a SynqNet object
***status**	pointer to a SynqNet status structure

Return Values

MPIMessageOK	if *meiSynqNetStatus* successfully gets the network status and writes it into the structure
MPIMessageARG_INVALID	if the status pointer is NULL

See Also

meiSqNodeStatus | meiSynqNetInfo

MEISynqNetMessageINVALID_COMPARE_COUNT	compare count value out of range, compare count exceeds compare resources supported by the node, or compare count is non-zero when encoder is disabled (feedbackCount == 0x0).
MEISynqNetMessageINVALID_INPUT_COUNT	ioInput count is out of range or it exceeds the count supported by the node.
MEISynqNetMessageINVALID_OUTPUT_COUNT	ioOutput count is out of range or it exceeds the count supported by the node.
MEISynqNetMessageINVALID_MONITOR_CFG	monitorConfig is out of range or it exceeds the count supported by the node.
MPIMessageUNSUPPORTED	an sqNodeLib module is missing or it contains a corrupt a resource table.

See Also

meiSynqNetPacketConfigGet | MEISynqNetPacketCfgNode | MEISynqNetPacketCfg

meiSynqNetTiming

Declaration

```
long meiSynqNetTiming(MEISynqNet          synqNet,
                      MEISynqNetTiming    *timing);
```

Required Header stdmei.h

Description **SynqNetTiming** returns the network timing values to the location pointed to by ***timing** for the current operating network. This method can only be called in MEISynqNetStatus.state >= MEISynqNetStateSYNQ.

synqNet	handle to a valid SynqNet object.
***timing**	a pointer to a MEISynqNetTiming structure.

Return Values

MPIMessageOK	if *meiSynqNetTiming* successfully retrieves the network timing values.
MPIMessageARG_INVALID	if *timing equals NULL.

See Also MEISynqNetTiming | MEISynqNetState

meiSynqNetFlashTopologyClear

Declaration

```
long meiSynqNetFlashTopologyClear(MEISynqNet synqNet,
                                  MEIFlash flash);
```

Required Header

stdmei.h

Description

SynqNetFlashTopologyClear will clear the topology information that is saved in the controller's flash memory by meiSynqNetTopologySave().

Executing this method will disable the controller from comparing the discovered network topology with the topology saved in flash memory. But, during network initialization, the MPI Library still compares the topology stored in the controller's dynamic memory with the discovered topology. In both cases, the default service commands are sent to the nodes if the network initialization transitions to SYNQ (cyclic) mode.

WARNING: This is a low-level network configuration routine that will clear any SqNode or Motor configurations that use service commands.

The meiSynqNetFlashTopologyClear method will:

1. Shutdown the SynqNet network.
2. Reset SqNode and Motor configurations to their defaults. See MPI Object Configurations that use Service Commands.
3. Clear network topology information from Flash and Dynamic memory.
4. Initialize the SynqNet network.

synqNet	a handle to an MEISynqNet object whose network topology is to be cleared.
flash	is either a vaild MEIFlash handle or MPIHandleVOID. If flash is MPIHandleVOID, an MEIFlash object will be created and deleted internally.

Return Values

MPIMessageOK	if *meiSynqNetFlashTopologyClear* successfully clears the networks topology information. ***flash*** is either an MEIFlash handle or MPIHandleVOID. If ***flash*** is MPIHandleVOID, an MEIFlash object will be created and deleted internally.
MPISynqNetMessageTOPOLOGY_CLEAR	if topology information has already been cleared or if it has not yet been saved to flash.

See Also

Save/Clear Topology to Flash | meiSynqNetFlashTopologySave

meiSynqNetFlashTopologySave

Declaration

```
long meiSynqNetFlashTopologySave(MEISynqNet synqNet,
                                 MEIFlash flash);
```

Required Header

stdmei.h

Description

SynqNetFlashTopologySave will save the current SynqNet topology to the controller's flash memory.

After a power-on or network shutdown/init, the controller/MPI Library will compare the discovered network topology with the topology saved in flash memory. If the topology information matches, the controller will automatically transition the network to SYNQ (cyclic) mode and configured service commands are sent to the nodes.

WARNING: This is a low-level network configuration routine that will reset the SynqNet network.

The meiSynqNetFlashTopologySave method will:

1. Shutdown the SynqNet network.
2. Reset SqNode and Motor configurations to their defaults. See MPI Object Configurations that use Service Commands.
3. Save network topology information from Flash memory.
4. Initialize the SynqNet network.

synqNet	a handle to an MEISynqNet object whose network topology is to be saved.
flash	is either a valid MEIFlash handle or MPIHandleVOID. If flash is MPIHandleVOID, an MEIFlash object will be created and deleted internally.

Return Values

MPIMessageOK	if *meiSynqNetFlashTopologySave* successfully saves the current SynqNet topology to the controller's flash memory.
MPISynqNetMessageTOPOLOGY_SAVED	if topology information has already been saved to flash. You must clear network topology before saving another network topology to flash.

See Also

Save/Clear Topology to Flash | meiSynqNetFlashTopologyClear

meiSynqNetInit

Declaration

```
long meiSynqNetInit(MEISynqNet     synqNet);
```

Required Header

stdmei.h

Description

SynqNetInit initializes a SynqNet network. This method performs the same network initialization that is automatically done with mpiControlInit(…).

synqNet	a handle to a SynqNet object

Return Values

MPIMessageOK	if *SynqNetInit* successfully initializes the network
MPIMessageARG_INVALID	if the *eventMask* pointer is NULL.

See Also

meiSynqNetInfo | meiSynqNetStatus

meiSynqNetShutdown

Declaration

```
long meiSynqNetShutdown(MEISynqNet      synqNet);
```

Required Header stdmei.h

Description **SynqNetEventShutdown** disables a SynqNet network by shutting off cyclic data transmission from the controller to the nodes. This will cause the network state to transition to MEISynqNetStateDISCOVERY and nodes will go into a SynqLost state and disable their outputs.

synqNet	a handle to a SynqNet object

Return Values

MPIMessageOK	if *meiSynqNetShutdown* successfully disables a SynqNet network by shutting off cyclic data transmission from the controller to the nodes.

See Also meiSynqNetInit | mpiControlReset | mpiControlInit | meiSynqNetStatus

meiSynqNetEventNotifyGet

Declaration

```
long meiSynqNetEventNotifyGet(MEISynqNet     synqNet,
                              MPIEventMask   *eventMask,
                              void           *external);
```

Required Header

stdmei.h

Description

SynqNetEventNotifyGet reads the event mask (that specifies the event types for which host notification has been requested) to the location pointed to by eventMask, and also writes it into the implementation specific location pointed to by external. (if external is not NULL).

Use the event mask macros mpiEventMaskGET(…), mpiEventMaskBitGET(…), etc. to decode the eventMask.

The event notification data in external is in addition to the event notification data in eventMask. If either eventMask is NULL or external is NULL (not both), then the event notification data will not be copied to the NULL pointer.

synqNet	a handle to a SynqNet object
***eventMask**	pointer to an event mask, whose bits are defined by the MPI/MEIEventType enumerations.
***external**	pointer to external

XMP Only

external either points to a structure of type MEIEventNotifyData{…} or is NULL.

The MEIEventNotifyData{…} structure is an array of controller addresses, whose contents are placed into the MEIEventStatusInfo{…} structure (of all events generated by this object).

Return Values

MPIMessageOK	if *meiSynqNetEventNotifyGet* successfully reads the event mask
MPIMessageARG_INVALID	if the *eventMask* pointer is NULL.

See Also

MEI/MPIEventType | MEIEventNotifyData | MEIEventStatusInfo

meiSynqNetEventNotifySet

Declaration

```
long meiSynqNetEventNotifySet(MEISynqNet     synqNet,
                              MPIEventMask   eventMask,
                              void           *external);
```

Required Header

stdmei.h

Description

SynqNetEventNotifySet requests host notification of the event(s) that are generated by ***SynqNet*** and specified by ***eventMask***, and also specified by the implementation specific location pointed to by ***external*** (if external is not NULL).

Use the event mask macros meiEventMaskSYNQNET(…), mpiEventMaskSET(…), mpiEventMaskBitSET(…), mpiEventMaskCLEAR(…), etc. to create the eventMask.

The event notification data in ***external*** is in addition to the event notification data in ***eventMask***. If either ***eventMask*** is NULL or ***external*** is NULL (not both), then the event notification data will not be copied to the NULL pointer.

synqNet	a handle to a SynqNet object
eventMask	pointer to an event mask, whose bits are defined by the MPI/MEIEventType enumerations.
***external**	pointer to external

XMP Only

external either points to a structure of type MEIEventNotifyData{…} or is NULL.

The MEIEventNotifyData{…} structure is an array of controller addresses, whose contents are placed into the MEIEventStatusInfo{…} structure (of all events generated by this object).

Return Values

MPIMessageOK	if *SynqNetEventNotifySet* successfully writes the event mask
MPIMessageARG_INVALID	if the eventMask pointer is NULL

See Also

MEI/MPIEventType | MEIEventNotifyData | MEIEventStatusInfo

meiSynqNetEventReset

Declaration

```
long meiSynqNetEventReset(MEISynqNet     synqNet,
                          MEIEventMask   eventMask);
```

Required Header

stdmei.h

Description

SynqNetEventReset resets the status/event bits that are specified in the eventMask and generated by the synqNet object. After a SynqNet event occurs, SynqNetEventReset should be called to reset the latched status/event bits so the specified event(s) can be generated again.

synqNet	a handle to a SynqNet object
eventMask	An array that defines the event mask bits. The array is defined as: `typedef MPIEventMaskELEMENT_TYPE MPIEventMask[MPIEventMaskELEMENTS]` The bits are defined by the MPI/MEIEventType enumerations.

Return Values

MPIMessageOK	if *meiSynqNetEventReset* successfully resets the status/event bits that are specified in the eventMask and generated by the synqNet object.

See Also

meiSynqNetStatus | meiSqNodeEventReset | meiSqNodeStatus

meiSynqNetControl

Declaration

```
meiSynqNetControl(MEISynqNet  synqNet);
```

Required Header

stdmei.h

Description

SynqNetControl returns a handle to the control object associated with the ***SynqNet*** object.

synqNet	a handle to a SynqNet object

Return Values

MPIControl	a handle to a control object.
MPIHandleVOID	if synqNet is not valid.

See Also

meiSynqNetCreate | mpiControlCreate

meiSynqNetNumber

Declaration

```
long meiSynqNetNumber(MEISynqNet   synqNet,
                      long         *number);
```

Required Header

stdmei.h

Description

SynqNetNumber reads the index of a SynqNet network and writes it into the contents of a long pointed to by number. Each SynqNet network associated with a controller is indexed by an identification number (0, 1, 2, etc.).

synqNet	a handle to a SynqNet object.
***number**	a pointer to the index of a SynqNet network.

Return Values

MPIMessageOK	if *SynqNetNumber* successfully reads the network number.

See Also

meiSynqNetInfo

MEISynqNetPacketCfgNode

MEISynqNetPacketCfgNode

```
typedef struct MEISynqNetPacketCfgNode {
     MEISynqNetPacketCfgMotor   motor[MEISynqNetMaxNodeMOTORS]
     MEISynqNetPacketCfgIo      io;
     long                       feedbackSecondaryCount;
} MEISynqNetPacketCfgNode;
```

Description

The **SynqNetPacketCfgNode** structure is a member of the MEISynqNetPacketCfg configuration structure. It contains the network packet configuration for all motors found on a particular node. Only configurable packet data is represented in this structure. Fixed packet fields are not application configurable.

motor	An array of configurable packet structures for motor data. Array indices 0 through MEISqNodeInfo.motorCount are valid, with a maximum number of motors per node being defined by MEISynqNetMaxNodeMOTORS.
io	Configures the network data packets general purpose node I/O.
feedbackSecondaryCount	Configures the number of 32-bit secondary feedback data fields to be sent for a node. Valid numbers are zero thru MEISynqNetMaxMotorFEEDBACK_SECONDARY_COUNT, but may be further limited by the available resources on the node.

See Also

meiSynqNetPacketConfigGet | meiSynqNetPacketConfigSet | MEISynqNetPacketCfg |

MEISynqNetCableLength

MEISynqNetCableLength

```
typedef struct MEISynqNetCableLength {  /* lengths in meters */
    long minimum;
    long nominal;
    long maximum;
} MEISynqNetCableLength;
```

Description

The **SynqNetCableLength** structure contains the nominal (average), minimum and maximum length in meters for a given network cable.

To disable the cable length checking feature, set the **minimum**, **nominal**, and **maximum** values to zero.

minimum	Minimum cable length in meters. A value less than zero or greater than the nominal value is invalid.
nominal	Nominal cable length in meters. A value less than zero is invalid.
maximum	Maximum cable length in meters. A value less than the nominal value is invalid.

See Also

MEISynqNetConfig | meiSynqNetConfigSet | meiSynqNetConfigSet | meiSynqNetInfo

MEISynqNetCableList

MEISynqNetCableList

```
typedef struct MEISynqNetCableList {
    long    count;
    long    cableNumber[MEISynqNetCableHOP_COUNT];
} MEISynqNetCableList;
```

Description

The **SynqNetCableList** structure contains the number of cables in the SynqNet network and their identifying numbers. The idle cables can be identified with the meiSynqNetIdleCableListGet(…) method.

A cable can also be identified by the node number and port. Use meiSynqNetCableNumToNodePort(...) to translate the cable number to a node number and a port.

count	The number of cables and number of valid elements in the cableNumber[] array.. Range is 0 to MEISynqNetCableHOP_COUNT.
cableNumber	The cables identified by their number. Cables are numbered in the order they are discovered during network initialization.

See Also

meiSynqNetIdleCableListGet | meiSynqNetIdleCableStatus | meiSynqNetCableNumToNodePort

MEISynqNetStatus

MEISynqNetStatus

```
typedef struct MEISynqNetStatus {
    MEISynqNetState             state;
    long                        topologySaved;  /* TRUE/FALSE */
    MEISynqNetStatusCrcError    crcError;
    MPIEventMask                eventMask;
    MEISynqNetFailedNodeMask    failedNodeMask;
} MEISynqNetStatus;
```

Description

The **SynqNetStatus** structure contains network state information, CRC counters, eventMask, and the failedNodeMask for a SynqNet network. The network status can be read with the meiSynqNetStatus(…) method.

state	Present operation mode for the network.
topologySaved	Contains the status of the network topology. FALSE means the topology is dynamically discovered at initialization. TRUE means that the topology is verified against an expected topology at initialization. See Saving Current Topology To Flash for more information.
crcError	CRC error counters for the controller's network ports. The CRC value increments when received data is corrupt. Range is from 0 to 255. Counter saturates at 255.
eventMask	An array that defines the status for the event mask bits. The array is defined as: `typedef MPIEventMaskELEMENT_TYPE MPIEventMask[MPIEventMaskELEMENTS]` The bits are defined by the MPI/MEIEventType enumerations.

failedNodeMask	Array that defines the failed node mask bits. Each bit represents a failed node (0x1 = node 0, 0x2 = node 2, 0x4 = node 3, etc.). The array is defined as:
	
	`#define MEISynqNetNodeMaskELEMENTS (1)`
	`typedef long MEISynqNetFailedNodeMask[MEISynqNetNodeMaskELEMENTS];`

See Also

meiSynqNetStatus | meiSqNodeStatus | MEISqNodeStatus

MEISynqNetRecoveryMode

MEISynqNetRecoveryMode

```
typedef enum MEISynqNetRecoveryMode {
    MEISynqNetRecoveryModeDISABLED,
    MEISynqNetRecoveryModeSINGLE_SHOT,
    MEISynqNetRecoveryModeAUTO_ARM,
} MEISynqNetRecoveryMode;
```

Description

SynqNetRecoveryMode is an enumeration of a network's fault recovery mode. Networks with ring topologies can be configured to recover from a fault condition. A fault condition occurs when a packet error rate counter exceeds its packet error rate fault limit. If fault recovery is enabled and a fault occurs, the node hardware and/or controller will detect the location of the fault and switch the direction of network traffic for nodes downstream from the faulted connection. During fault recovery, the network state is MEISynqNetStateSYNQ_RECOVERING. After the upstream and downstream packet error rate counters decrement to zero, the recovery is completed, and the network state returns to MEISynqNetStateSYNQ.

When fault recovery occurs, the controller will generate a MEIEventTypeSYNQNET_RECOVERY status/event. An application should notify the user about the fault and fix the broken cable/hardware as soon as possible. An application can determine the location of the fault using meiSynqNetIdleCableListGet(...). A network with a ring topology has one idle cable, which has no data traffic. The operation of the idle cable can be tested with meiSynqNetIdleCableStatus(...).

WARNING: If the idle cable is broken and a second fault occurs, then fault recovery will not be able to fully recover from the fault. SynqNet will try to recover, but some nodes will be stranded. Presently, SynqNet does not support an event to notify the application if an idle cable fails. In the meantime, an application can periodically poll the idle cable with meiSynqNetIdleCableStatus(...) to test the cable.

MEISynqNetRecoveryModeDISABLED	The network will not attempt to recover from a fault condition. This is the default mode for string topologies.
MEISynqNetRecoveryModeSINGLE_SHOT	The network will only attempt to recover from a fault condition one time. A second fault will be ignored.
MEISynqNetRecoveryModeAUTO_ARM	The network will attempt to recover from a fault condition. After the fault recovery is complete, the network will automatically be re-armed to respond to another fault condition. This is the default mode for ring topologies.

See Also meiSynqNetConfigGet | meiSynqNetConfigSet | meiSynqNetStatus | meiSynqNetInfo | meiSynqNetIdleCableListGet | meiSynqNetIdleCableStatus

MEISynqNetFailedNodeMask

MEISynqNetFailedNodeMask

```
#define MEISynqNetNodeMaskELEMENTS  (1)
typedef long MEISynqNetFailedNodeMask  [MEISynqNetNodeMaskELEMENTS];
```

Description

SynqNetFailedNodeMask is an array of longs with a length of MEISynqNetNodeMaskELEMENTS. Each bit in the failed node mask represents a failed node (0x1 = node 0, 0x2 = node 2, 0x4 = node 3, etc.). A node failure occurs when the packet error rate counters exceed the packet error rate fail limit.

See Also

MEISynqNetStatus | meiSynqNetStatus | meiSqNodeStatus | MEISqNodeConfig

MEISynqNetMessage

MEISynqNetMessage

```
typedef enum {
    MEISynqNetMessageSYNQNET_INVALID,
    MEISynqNetMessageMAX_NODE_ERROR,
    MEISynqNetMessageSTATE_ERROR,

    MEISynqNetMessageCOMM_ERROR,
    MEISynqNetMessageCOMM_ERROR_CRC,
    MEISynqNetMessageCOMM_ERROR_RX,
    MEISynqNetMessageCOMM_ERROR_RX_LEN,
    MEISynqNetMessageCOMM_ERROR_RX_FIFO,
    MEISynqNetMessageCOMM_ERROR_RX_DRIBBLE,
    MEISynqNetMessageCOMM_ERROR_RX_CRC,

    MEISynqNetMessageINTERFACE_NOT_FOUND,
    MEISynqNetMessageTOPOLOGY_MISMATCH,
    MEISynqNetMessageTOPOLOGY_MISMATCH_FLASH,

    MEISynqNetMessageRESET_REQ_TIMEOUT,
    MEISynqNetMessageRESET_ACK_TIMEOUT,
    MEISynqNetMessageDISCOVERY_TIMEOUT,
    MEISynqNetMessageNO_NODES_FOUND,

    MEISynqNetMessageNO_TIMING_DATA_AVAIL,

    MEISynqNetMessageINTERNAL_BUFFER_OVERFLOW,
    MEISynqNetMessageINVALID_MOTOR_COUNT,
    MEISynqNetMessageINVALID_AUX_ENC_COUNT,
    MEISynqNetMessageINCOMPLETE_MOTOR,
    MEISynqNetMessageINVALID_COMMAND_CFG,
    MEISynqNetMessageINVALID_ENCODER_COUNT,
    MEISynqNetMessageINVALID_CAPTURE_COUNT,
    MEISynqNetMessageINVALID_COMPARE_COUNT,
    MEISynqNetMessageINVALID_INPUT_COUNT,
    MEISynqNetMessageINVALID_OUTPUT_COUNT,
    MEISynqNetMessageINVALID_MONITOR_CFG,
    MEISynqNetMessageINVALID_ANALOG_IN_COUNT,

    MEISynqNetMessageLINK_NOT_IDLE,
    MEISynqNetMessageIDLE_LINK_UNKNOWN,
    MEISynqNetMessageRING_ONLY,
    MEISynqNetMessageRECOVERING,

    MEISynqNetMessageCABLE_LENGTH_UNSUPPORTED,
    MEISynqNetMessageCABLE_LENGTH_MISMATCH,
    MEISynqNetMessageCABLE_LENGTH_INVALID_NOMINAL,
    MEISynqNetMessageCABLE_LENGTH_INVALID_MIN,
    MEISynqNetMessageCABLE_LENGTH_INVALID_MAX,
```

```
    MEISynqNetMessageNODE_FPGA_VERSION,
    MEISynqNetMessageMAX_NODE_ERROR,
    MEISynqNetMessagePLL_ERROR,
    MEISynqNetMessageNODE_INIT_FAIL,

    MEISynqNetMessageTOPOLOGY_CLEAR,
    MEISynqNetMessageTOPOLOGY_SAVED,

    MEISynqNetMessageNODE_MAC_VERSION,
    MEISynqNetMessageADC_SAMPLE_FAILURE,

  MEISynqNetMessageSCHEDULING_ERROR,
       MEISynqNetMessageINVALID_PROBE_CFG,
       MEISynqNetMessageINVALID_PROBE_DEPTH,

} MEISynqNetMessage;
```

Description

SynqNetMessage is an enumeration of SynqNet error messages that can be returned by the MPI library.

MEISynqNetMessageSYNQNET_INVALID

The SynqNet number is out of range. This message code is returned by meiSynqNetCreate(…) if the SynqNet network number is less than zero or greater than or equal to MEIXmpMaxSynqNets.

MEISynqNetMessageMAX_NODE_ERROR

The SynqNet node number is out of range. This message code is returned by a SynqNet method if the specified node number is greater than or equal to MEIXmpMaxSynqNetBlocks.

MEISynqNetMessageSTATE_ERROR

The SynqNet network state is not valid. This message code is returned by any method that initializes a SynqNet network if the controller's network state is not a member of the MEIXmpSynqNetState or MEIXmpSynqNetInternalState enumeration. The most commonly used methods that initialize the SynqNet network are: mpiControlInit(…), mpiControlReset(…) and meiSynqNetInit(…). This message code indicates a failure in the controller's initialization sequence. To correct this problem, call mpiControlReset(…).

MEISynqNetMessageCOMM_ERROR

The SynqNet network communication failed. This message code is returned by MPI methods that fail a service command transaction due to a network shutdown. This message indicates a node or network cable failure. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageCOMM_ERROR_CRC

The SynqNet network communication failed due to excessive CRC errors. This message code is returned by MPI methods that fail a service command transaction due to a network shutdown. This message indicates a node or network cable failure. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageCOMM_ERROR_RX

The SynqNet network communication failed due to a Rincon receive error. This message code is returned by MPI methods that fail a service command transaction due to a network shutdown. This message indicates a node or network cable failure. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageCOMM_ERROR_RX_LEN

The SynqNet network communication failed due to a Rincon receive length error. This message code is returned by MPI methods that fail a service command transaction due to a network shutdown. This message indicates a node or network cable failure. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageCOMM_ERROR_RX_FIFO

The SynqNet network communication failed due to a Rincon receive buffer error. This message code is returned by MPI methods that fail a service command transaction due to a network shutdown. This message indicates a node or network cable failure. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageCOMM_ERROR_RX_DRIBBLE

The SynqNet network communication failed due to a Rincon receive dribble error. This message code is returned by MPI methods that fail a service command transaction due to a network shutdown. This message indicates a node or network cable failure. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageCOMM_ERROR_RX_CRC

The SynqNet network communication failed due to a Rincon receive CRC error. This message code is returned by MPI methods that fail a service command transaction due to a network shutdown. This message indicates a node or network cable failure. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageINTERFACE_NOT_FOUND

The controller does not support a SynqNet interface. This message code is returned by meiSynqNetValidate(…), meiSynqNetFlashTopologySave(…), meiSynqNetFlashTopologyClear(…), mpiControlInit(…), and mpiControlReset(…) if the controller does not have a SynqNet hardware interface. To correct this problem, use a controller that supports SynqNet.

MEISynqNetMessageTOPOLOGY_MISMATCH

The network topology does not match the expected network topology. This message code is returned by mpiControlInit(…) or meiSynqNetInit(…) if the discovered network topology does not match the controller's expected network topology (stored in dynamic memory). During the first network initialization the controller stores node identification information (manufacturer, product, and unique values) into it's dynamic memory. This message code indicates the number of nodes, the node order, or types of nodes have changed since the initial network initialization. To correct this problem, either change the network topology to the original configuration or clear the controller's memory with mpiControlReset(…).

MEISynqNetMessageTOPOLOGY_MISMATCH_FLASH

The network topology does not match the expected network topology. This message code is returned by mpiControlInit(…) or meiSynqNetInit(…) if the discovered network topology does not match the controller's expected network topology (stored in flash memory). During the first network initialization the controller stores node identification information (manufacturer, product, and unique values) into it's dynamic memory. Later, when meiSynqNetFlashTopologySave(…) is called, the topology information is stored into flash memory. This message indicates the number of nodes, the node order, or types of nodes have changed since the topology information was stored in flash. To correct this problem, either change the network topology to the saved configuration or clear the controller's flash topology with meiSynqNetFlashTopologyClear(…).

MEISynqNetMessageRESET_REQ_TIMEOUT

The network reset request packet exceeded the timeout. This message code is returned by mpiControlInit(…), mpiControlReset(…), or meiSynqNetInit(…) if the reset request packet fails to traverse the network in the allotted time. This message code indicates a node or network cable failure. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageRESET_ACK_TIMEOUT

The network reset complete packet exceeded the timeout. This message code is returned by mpiControlInit(…), mpiControlInit(…), or meiSynqNetInit(…) if the reset complete packet fails to traverse the network in the allotted time. This message code indicates a node or network cable failure. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageDISCOVERY_TIMEOUT

The network topology discovery exceeded the timeout. This message code is returned by mpiControlInit(…), mpiControlInit(…), or meiSynqNetInit(…) if the controller failed to discover the network topology in the allotted time. This message code indicates a node or network cable failure. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageNO_NODES_FOUND

The controller did not find network nodes. This message code is returned by mpiControlInit(…), meiSynqNetPacketConfigSet(…), or meiSynqNetInit(…) if the controller failed to discover any nodes during network initialization. This message code indicates the first node has failed or the network connection from the controller to the first node is faulty. To correct this problem, check your network wiring and node condition.

MEISynqNetMessageNO_TIMING_DATA_AVAIL

The corresponding SynqNet node module does not contain timing data, so the network cannot be initialized. Contact MEI or drive manufacturer for an updated node module.

MEISynqNetMessageINTERNAL_BUFFER_OVERFLOW

The controller's SynqNet buffer size was exceeded. This message code is returned by mpiControlInit(…), mpiControlReset(…), or meiControlInit(…) if the controller's SynqNet buffer could not be allocated due to overflow. This message code indicates the controller does not have enough memory to initialize the network topology. To correct the problem, either reduce the network nodes or use a different controller model.

MEISynqNetMessageINVALID_MOTOR_COUNT

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains more motors than supported by the node.

MEISynqNetMessageINVALID_AUX_ENC_COUNT

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains more secondary encoders than supported by the node.

MEISynqNetMessageINCOMPLETE_MOTOR

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains a motor configuration that is missing feedback or command fields.

MEISynqNetMessageINVALID_COMMAND_CFG

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains a different command configuration than is supported by the node.

MEISynqNetMessageINVALID_ENCODER_COUNT

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains more encoders than supported by the node.

MEISynqNetMessageINVALID_CAPTURE_COUNT

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains a larger capture count than is supported by the node.

MEISynqNetMessageINVALID_COMPARE_COUNT

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains a larger compare count than is supported by the node.

MEISynqNetMessageINVALID_INPUT_COUNT

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains a larger ioInput count than is supported by the node.

MEISynqNetMessageINVALID_OUTPUT_COUNT

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains a larger ioOutput count than is supported by the node.

MEISynqNetMessageINVALID_MONITOR_CFG

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains more monitor fields than the node can support.

MEISynqNetMessageINVALID_ANALOG_IN_COUNT

This message is returned by meiSynqNetPacketConfigSet(…), when the packet configuration contains a larger analogIn count than is supported by the node.

MEISynqNetMessageLINK_NOT_IDLE

This message is returned by meiSynqNetIdleCableStatus(...) when the cable number supplied is not the idle link. The status check can only be run on an idle cable. See meiSynqNetIdleCableListGet(…).

MEISynqNetMessageIDLE_LINK_UNKNOWN

This message is returned by meiSynqNetIdleCableListGet(…) when an idle cable number in a ring topology cannot be determined. This is due to one or more failed nodes on a ring topology. Be sure to check the status of the nodes.

MEISynqNetMessageRECOVERING

The network is recovering from a fault condition. This message is returned by meiSynqNetIdleCableStatus(...) during network fault recovery, because the network traffic is being redirected around the faulted cable and a new idle cable is in the process of being assigned. If you receive this message, wait for recovery to complete and then check the identity of the idle cable with meiSynqNetIdleCableListGet(…).

MEISynqNetMessageRING_ONLY

This message is returned by meiSynqNetIdleCableListGet(…) and meiSynqNetIdleCableStatus(...) because idle cables exist on ring topologies only. It is also returned by meiSynqNetConfigSet(...) when attempting to enable SynqNet recovery mode, which is only supported for ring topologies.

MEISynqNetMessageCABLE_LENGTH_UNSUPPORTED

This message is returned when a cable on the network is too long.

MEISynqNetMessageCABLE_LENGTH_MISMATCH

This message is returned at network initialization when topology has been saved to flash and a cable length is detected that lies outside the MEISynqNetConfig.cableLength[n].minimum and maximum. Check cable length (if necessary) and save new cable length values to flash.

MEISynqNetMessageCABLE_LENGTH_INVALID_NOMINAL

The nominal cable length is too long.

MEISynqNetMessageCABLE_LENGTH_INVALID_MIN

The minimum cable length is too long or exceeds nominal value.

MEISynqNetMessageCABLE_LENGTH_INVALID_MAX

The maximum cable length is too long or is less than nominal value.

MEISynqNetMessageNODE_FPGA_VERSION

The node resource FPGA image is out of date. This is only a warning message. Your network will still reach cyclic (SYNQ) mode, but certain node resources may not be available or may not operate as expected. Only ignore this warning if you are aware of FPGA changes between this version and the version built with the MPI or use the sqNodeFlash.exe utility to load the most current FPGA version to the node.

MEISynqNetMessageMAX_NODE_ERROR

The number of motors on the network exceeds the number set by MEISynqNetMaxMOTORS.

MEISynqNetMessagePLL_ERROR

The node PLL is unable to lock with drive.

MEISynqNetMessageNODE_INIT_FAIL

A node specific initialization routine was unable to complete successfully. Verify node FPGA is the default version for your MPI version. See MEISqNodeInfoFpga.defaultVersion.

MEISynqNetMessageTOPOLOGY_CLEAR

An attempt to clear the saved network topology was made when no network topology has been saved.

MEISynqNetMessageTOPOLOGY_SAVED

An attempt to save network topology was made when the network topology has already been saved. Clear the network topology before attempting to save another topology to flash.

MEISynqNetMessageNODE_MAC_VERSION

The node MAC FPGA image is out of date. This is an error message. Your network will probably never reach cyclic (SYNQ) mode. Use the sqNodeFlash.exe utility to load the most current FPGA version tothe node.

MEISynqNetMessageADC_SAMPLE_FAILURE

A check to verify that all analog inputs can be sampled during the given controller sample rate has failed. Either reduce the number of analog inputs on your network (see meiSynqNetPacketConfigGet / meiSynqNetPacketConfigSet) or decrease your controller sample rate (see mpiControlConfigGet / mpiControlConfigSet).

MEISynqNetMessageSCHEDULING_ERROR

This is a generic return value to indicate that a problem has occurred while calculating the network scheduling. For more specific information about the error, run your application with timing assignment tracing turned on, using the trace mask:

0x00100000 SynqNet: Display timing assignments

MEISynqNetMessageINVALID_PROBE_CFG

This message is returned by meiSynqNetPacketConfigSet(…), when the MEISynqNetPacketCfgProbe.count contains a larger count than is supported by the node.

MEISynqNetMessageINVALID_PROBE_DEPTH

This message is returned by meiSynqNetPacketConfigSet(…), when the MEISynqNetPacketCfgProbe.depth contains a larger count than is supported by the node.

See Also

MEISynqNetPacketCfgProbe

MEISynqNetPacketCfgProbe

```
typedef struct MEISynqNetPacketCfgProbe {
     long                                count;
     MEISynqNetResourceProbeDepth        depth[MEISynqNetMaxMotorPROBE_COUNT];
} MEISynqNetPacketCfgNode;
```

Description

The **SynqNetPacketCfgProbe** structure specifies the network packet configuration for all the Probes found on a particular motor. Only configurable packet data is represented in this structure. Fixed packet fields are not application configurable.

count	the number of Probe engines per motor. Each Probe engine requires cyclic packet data for the status fields.
depth	an array of enumerated values representing the Probe data depth. Each probe engine can support up to 16 register fields for the probe data. The length of the array is specified by the Probe count.

See Also

MEISynqNetPacketCfgMotor | MEISynqNetResourceProbeDepth | MPIProbeStatus

MEISynqNetResourceCommand

MEISynqNetResourceCommand

```
typedef enum MEISynqNetResourceCommand {
    MEISynqNetResourceCommandINVALID,
    MEISynqNetResourceCommandNONE,
    MEISynqNetResourceCommandDAC_ONE,
    MEISynqNetResourceCommandDAC_TWO,
    MEISynqNetResourceCommandDEMAND_A,
    MEISynqNetResourceCommandDEMAND_ABC,
} MEISynqNetResourceCommand;
```

Description

The **SynqNetResourceCommand** enumeration is a member of the MEISynqNetPacketCfgMotor configuration structure. The values are used to configure the number of 32-bit command data fields sent to drive a motor. Valid values range from greater or equal to MEISynqNetResourceCommandFIRST and less than MEISynqNetResourceCommandLast, but may be further limited by the available resources on the node.

NOTE: A motor is considered incomplete if it has a command value of NONE.

MEISynqNetResourceCommandINVALID	Non-vaild command value was detected.
MEISynqNetResourceCommandNONE	No command data will be sent to this motor. NOTE: this disables the motor and will require the application to remove all other resources for this motor.
MEISynqNetResourceCommandDAC_ONE	Configures a 32bit data field of DAC data to besent to the motor.
MEISynqNetResourceCommandDAC_TWO	Configures two 32bit data fields of DAC data to besent to the motor.
MEISynqNetResourceCommandDEMAND_A	Configures one 16bit data field of Demand data to be sent to the motor.
MEISynqNetResourceCommandDEMAND_ABC	Configures three 16bit data fields of Demand data to be sent to the motor.

See Also meiSynqNetPacketConfigGet | meiSynqNetPacketConfigSet | MEISynqNetPacketCfgMotor | MEISynqNetPacketCfg | MEISynqNetPacketCfgNode

MEISynqNetPacketCfgMotor

MEISynqNetPacketCfgMotor

```
typedef struct MEISynqNetPacketCfgMotor {
    MEISynqNetResourceCommand   command;
    long                        pulseEngineCount;
    long                        feedbackPrimaryCount;
    long                        captureCount;
    long                        compareCount;
    MEISynqNetResourceIoBits    ioInput;
    MEISynqNetResourceIoBits    ioOutput;
    MEISynqNetResourceMonitor   monitor;
    MEISynqNetPacketCfgProbe    probe;
} MEISynqNetPacketCfgMotor;
```

Description

The **SynqNetPacketCfgMotor** structure is a member of the MEISynqNetPacketCfgNode configuration structure. It contains the network packet configuration for a single motor found on a particular node. Only configurable packet data is represented in this structure. Fixed packet fields are not application configurable.

NOTE: Setting all structure members to a NONE or Zero (0x0) value will effectively disable the motor on the network. This will cause the controller to renumber the subsequent motors on the network.

command	Selects the command data type and count. Please see MEISynqNetResourceCommand.
pulseEngineCount	Configures the number of pulse engine to be enable for a motor. Valid numbers are zero thru MEISynqNetMaxMotorPULSE_ENGINE_COUNT, but may be further limited by the available resources on the node. Each pulse engine requires a 64-bit upstream data field and a 32-bit downstream data field.
feedbackPrimaryCount	Configures the number of 32-bit feedback data fields to be sent for a motor. Valid numbers are zero thru MEISynqNetMaxEncoderFEEDBACK_COUNT, but may be further limited by the available resources on the node.

captureCount	Configures the number of 32-bit capture data fields to be sent for a motor. Valid numbers are zero thru MEISynqNetMaxMotorCAPTURE_COUNT, but may be further limited by the available resources on the node. If feedbackCount is zero (0x0), then this value must also be zero. **NOTE**: All capture/compare resources on a motor rely on two fixed 32bit data fields for command and status information. These fixed fields are currently not configurable.
compareCount	Configures the number of 32-bit compare data fields to be sent for a motor. Valid numbers are zero thru MEISynqNetMaxMotorCOMPARE_COUNT, but may be further limited by the available resources on the node. **NOTE**: all capture/compare resources on a motor rely on two fixed 32bit data fields for command and status information. These fixed fields are currently not configurable.
ioInput	Selects the number of input bit data received from this motor. Please see MEISynqNetResourceIoBits.
ioOutput	Selects the number of output bit data sent to this motor. Please see MEISynqNetResourceIoBits.
monitor	Selects the number of montior data fields received from this motor. Please see MEISynqNetResourceMonitor.
probe	A structure that specifies the probe count and register depth.

See Also

meiSynqNetPacketConfigGet | meiSynqNetPacketConfigSet | MEISynqNetPacketCfg | MEISynqNetPacketCfgNode | MEISynqNetResourceCommand | MEISynqNetResourceIoBits | MEISynqNetResourceMonitor | MEISynqNetPacketCfgProbe

MEISynqNetResourceIoBits

MEISynqNetResourceIoBits

```
typedef enum MEISynqNetResourceIoBits {
    MEISynqNetResourceIoBitsINVALID,
    MEISynqNetResourceIoBitsNONE,
    MEISynqNetResourceIoBits16,
    MEISynqNetResourceIoBits48,
} MEISynqNetResourceIoBits;
```

Description

The **SynqNetResourceIoBits** enumeration is a member of the MEISynqNetPacketCfgMotor configuration structure. The values are used to configure the number of I/O data fields sent to a motor. Valid values range from greater or equal to MEISynqNetResourceIoBitsFIRST and less than MEISynqNetResourceIoBitsLAST, but may be further limited by the available resources on the node. This is a generic enumeration that is used to configure the resource count of different types of motor and node I/O.

NOTE: (for Motor I/O only) Enabled motors always contain one fixed 16bit data field of dedicated I/O. This is not application configurable.

MEISynqNetResourceIoBitsINVALID	Non-valid bit count was detected.
MEISynqNetResourceIoBitsNONE	No I/O bits will be sent/received.
MEISynqNetResourceIoBits16	One data field of 16 I/O bits will be sent/received.
MEISynqNetResourceIoBits48	One data field of 48 I/O bits will be sent/received.

See Also

meiSynqNetPacketConfigGet | meiSynqNetPacketConfigSet | MEISynqNetPacketCfgMotor | MEISynqNetPacketCfg | MEISynqNetPacketCfgNode | mpiMotorIoGet | mpiMotorIoSet

MEISynqNetResourceMonitor

MEISynqNetResourceMonitor

```
typedef enum MEISynqNetResourceMonitor {
    MEISynqNetResourceMonitorINVALID,
    MEISynqNetResourceMonitorNONE,
    MEISynqNetResourceMonitorAB,
    MEISynqNetResourceMonitorABCD,
} MEISynqNetResourceMonitor;
```

Description

The **SynqNetResourceMonitor** enumeration is a member of the MEISynqNetPacketCfgMotor configuration structure. The values are used to configure the number of Monitor data fields received from a motor. Valid values range from greater or equal to MEISynqNetResourceMonitorFIRST and less than MEISynqNetResourceMonitorLAST, but may be further limited by the available resources on the node.

MEISynqNetResourceMonitorINVALID	Non-valid bit count was detected.
MEISynqNetResourceMonitorNONE	No monitor data fields will be sent/received for this motor.
MEISynqNetResourceMonitorAB	Two 16bit fields of monitor data will be sent/received for this motor.
MEISynqNetResourceMonitorABCD	Four 16bit fields of monitor data will be sent/received for this motor.

See Also

MEISynqNetResourceCfgProbeDepth

MEISynqNetResourceCfgProbeDepth

```
typedef enum MEISynqNetResourceProbeDepth {
    MEISynqNetResourceProbeDepthNONE,
    MEISynqNetResourceProbeDepthTWO,
    MEISynqNetResourceProbeDepthFOUR,
    MEISynqNetResourceProbeDepthEIGHT,
    MEISynqNetResourceProbeDepthSIXTEEN,
} MEISynqNetResourceProbeDepth;
```

Description

The **SynqNetPacketCfgProbeDepth** is an enumeration of the possible Probe register depths. Each Probe register is 16 bits. The packet data size is 32 bits. Each Probe engine can support up to 16 register fields for the Probe data.

MEISynqNetResourceProbeDepthNONE	zero Probe data registers will be transmitted upstream
MEISynqNetResourceProbeDepthTWO	2 Probe data registers will be transmitted upstream
MEISynqNetResourceProbeDepthFOUR	4 Probe data registers will be transmitted upstream
MEISynqNetResourceProbeDepthEIGHT	8 Probe data registers will be transmitted upstream
MEISynqNetResourceProbeDepthSIXTEEN	16 Probe data registers will be transmitted upstream

See Also

MEISynqNetPacketCfgEncoder

MEISynqNetPacketCfgEncoder

```
typedef struct MEISynqNetPacketCfgEncoder {
    long feedbackCount;    /* per encoder */
    long captureCount;     /* per encoder */
    long compareCount;     /* per encoder */
} MEISynqNetPacketCfgEncoder;
```

Description

The **SynqNetPacketCfgEncoder** structure is a member of the MEISynqNetPacketCfgMotor configuration structure. It contains the network packet configuration for a single encoder found on a particular motor. Only configurable packet data is represented in this structure. Fixed packet fields are not application configurable.

Setting all structure members to zero (0x0) values will effectively disable the encoder on the motor. Disabling an encoder will NOT affect encoder numbering, however, encoders with higher index numbers must be disabled before using encoders with lower index numbers.

NOTE: A motor is considered incomplete if it has no encoders enabled.

feedbackCount	configures the number of 32-bit feedback data fields to be sent for an encoder. Valid numbers are zero thru MEISynqNetMaxEncoderFEEDBACK_COUNT , but may be further limited by the available resources on the node. **NOTE**: Setting this count to a value of zero (0x0) will affectively disable the encoder. All other encoder resources must also be set to NONE or zero (0x0).
captureCount	configures the number of 32-bit capture data fields to be sent for an encoder. Valid numbers are zero thru MEISynqNetMaxMotorCAPTURE_COUNT, but may be further limited by the available resources on the node. If feedbackCount is zero (0x0), then this value must also be zero. **NOTE**: all capture/compare resources on a motor rely on 2 fixed 32bit data fields for command and status information. These fixed fields are currently not configurable.

compareCount	configures the number of 32-bit compare data fields to be sent for an encoder. Valid numbers are zero thru MEISynqNetMaxMotorCOMPARE_COUNT, but may be further limited by the available resources on the node. If feedbackCount is zero (0x0), then this value must also be zero. **NOTE**: all capture/compare resources on a motor rely on 2 fixed 32bit data fields for command and status information. These fixed fields are currently not configurable.

See Also

meiSynqNetPacketConfigGet | meiSynqNetPacketConfigSet | MEISynqNetPacketCfgMotor | MEISynqNetPacketCfg | MEISynqNetPacketCfgNode

MEISynqNetPacketCfgIo

MEISynqNetPacketCfgIo

```
typedef struct MEISynqNetPacketCfgIo {
    long   digitalInCount;
    long   digitalOutCount;
    long   analogInCount;
    long   analogOutCount;
} MEISynqNetPacketCfgIo;
```

Description

The **SynqNetPacketCfgIo** structure configures the network data packets that contain general purpose I/O.

digitalInCount	Selects the number of 32bit words of digital input data to receive over the SynqNet network.
digitalOutCount	Selects the number of 32bit words of digital output data to send over the SynqNet network.
analogInCount	Selects the number of 32bit words of analog input data to receive over the SynqNet network.
analogOutCount	Selects the number of 32bit words of analog output data to send over the SynqNet network.

See Also

meiSynqNetPacketConfigSet | meiSynqNetPacketConfigGet | MEISynqNetPacketCfgNode

MEISynqNetStatusCrcError

MEISynqNetStatusCrcError

```
typedef struct MEISynqNetStatusCrcError {
    long port[MEINetworkPortLAST];
} MEISynqNetStatusCrcError;
```

Description

The **SynqNetStatusCrcError** structure contains the CRC values for each network port on the controller. This structure is read via the meiSynqNetStatus(…) method.

port	an array of CRC values, one for each network port.

See Also

MEINetworkPort | MEISynqNetStatus | meiSynqNetStatus | CRC Error Counters

MEISynqNetTrace

MEISynqNetTrace

```
typedef enum {
    MEISynqNetTraceDYNA_ALLOC   = MEISynqNetTraceFIRST << 0,
    MEISynqNetTraceDYNA_FREE    = MEISynqNetTraceFIRST << 1,
    MEISynqNetTraceINIT         = MEISynqNetTraceFIRST << 2,
    MEISynqNetTraceRESET        = MEISynqNetTraceFIRST << 3,
    MEISynqNetTraceTIMING       = MEISynqNetTraceFIRST << 4,
    MEISynqNetTraceSERVICE_CMD  = MEISynqNetTraceFIRST << 5,
    MEISynqNetTraceFLOWCTRL     = MEISynqNetTraceFIRST << 6,
    MEISynqNetTraceMAP          = MEISynqNetTraceFIRST << 7,
    MEISynqNetTraceUNMAP        = MEISynqNetTraceFIRST << 8,

} MEISynqNetTrace;
```

Description

SynqNetTrace is an enumeration of SynqNet trace bits that can be used to enable/disable library trace statement output for the SynqNet object.

MEISynqNetTraceDYNA_ALLOC	Enables trace statements for controller external memory allocation during SynqNet initialization.
MEISynqNetTraceDYNA_FREE	Enables trace statements for controller external memory de-allocation.
MEISynqNetTraceINIT	Enables trace statements for SynqNet network initialization.
MEISynqNetTraceRESET	Enables trace statements for SynqNet network reset.
MEISynqNetTraceTIMING	Enables trace statements for SynqNet network timing calculations.
MEISynqNetTraceSERVICE_CMD	Enables trace statements for SynqNet service command transactions between the controller and SynqNet nodes.
MEISynqNetTraceFLOWCTRL	This trace bit enables trace statements for the SynqNet service command handshake between the controller and SynqNet nodes.
MEISynqNetTraceMAP	This trace bit enables trace statements for the mapping of firmware pointers to the dynamic controller memory.
MEISynqNetTraceUNMAP	This trace bit enables trace statements for the unmapping of firmware pointers from the dynamic controller memory.

See Also

Trace.exe utility

MEISynqNetMaxMOTORS

MEISynqNetMaxMOTORS

```
#define MEISynqNetMaxMOTORS (MEIXmpMAX_Motors) /* 32 */
```

Description

SynqNetMaxMOTORS defines the maximum number of motors supported on a single SynqNet network.

See Also

MEISynqNetMaxMotorFEEDBACK_SECONDARY_COUNT

MEISynqNetMaxMotorFEEDBACK_SECONDARY_COUNT

```
#define MEISynqNetMaxMotorFEEDBACK_SECONDARY_COUNT  (MEISqNodeMaxFEEDBACK_SECONDARY)
```

Description

SynqNetMaxMotorFEEDBACK_SECONDARY_COUNT defines the maximum number of secondary feedback resources per motor.

NOTE: Feedback count may be further limited by the available resources on the node.

See Also

MEISynqNetMaxMotorFEEDBACK_PRIMARY_COUNT

MEISynqNetMaxMotorFEEDBACK_PRIMARY_COUNT

```
#define MEISynqNetMaxMotorFEEDBACK_PRIMARY_COUNT  (1)
```

Description

SynqNetMaxMotorFEEDBACK_PRIMARY_COUNT defines the maximum number of primary feedback resources per motor.

NOTE: Feedback count may be further limited by the available resources on the node.

See Also

MEISynqNetMaxMotorCAPTURE_COUNT

MEISynqNetMaxMotorCAPTURE_COUNT

```
#define MEISynqNetMaxMotorCAPTURE_COUNT (MEIXmpMaxCapturesPerMotor) /*  2 */
```

Description

SynqNetMaxMotorCAPTURE_COUNT defines the maximum number of capture resources per motor.

NOTE: Capture count may be further limited by the available resources on the node.

This define should be used instead of the MEIXmpMaxCapturesPerMotor definition in xmp.h. It is recommended that applications avoid programming to defines or structures in xmp.h

See Also

MEISynqNetMaxMotorCOMPARE_COUNT

MEISynqNetMaxMotorCOMPARE_COUNT

```
#define MEISynqNetMaxMotorCOMPARE_COUNT (MEIXmpMaxCapturesPerMotor) /*  2 */
```

Description

SynqNetMaxMotorCOMPARE_COUNT defines the maximum number of compare resources per motor.

NOTE: Compare count may be further limited by the available resources on the node.

This define should be used instead of the MEIXmpMaxComparesPerMotor definition in xmp.h. It is recommended that applications avoid programming to defines or structures in xmp.h

See Also

MEISynqNetMaxMotorENCODER_COUNT

MEISynqNetMaxMotorENCODER_COUNT

```
#define MEISynqNetMaxMotorENCODER_COUNT (MEIXmpMotorEncoders) /*  2 */
```

Description

SynqNetMaxMotorENCODER_COUNT defines the maximum number of encoder resources per motor.

NOTE: The encoder count may be further limited by the available resources on the node.

This define should be used instead of the MEIXmpMotorEncoders definition in xmp.h. It is recommended that applications avoid programming to defines or structures in xmp.h

See Also

MEISynqNetMaxMotorPULSE_ENGINE_COUNT

MEISynqNetMaxMotorPULSE_ENGINE_COUNT

```
#define MEISynqNetMaxMotorPULSE_ENGINE_COUNT  (1)
```

Description

SynqNetMaxMotorPULSE_ENGINE_COUNT defines the number of pulse engines per motor.

See Also

MEISynqNetMaxNodeMOTORS

MEISynqNetMaxNodeMOTORS

```
#define MEISynqNetMaxNodeMOTORS (MEISqNodeMaxMOTORS)
```

Description

SynqNetMaxNodeMOTORS defines the maximum number of motor objects supported on a single SynqNet node.

See Also

MEISynqNetMaxNODE_COUNT

MEISynqNetMaxNODE_COUNT

```
#define MEISynqNetMaxNODE_COUNT (MEIXmpMaxSynqNetBlocks) /* 32 */
```

Description

SynqNetMaxNODE_COUNT defines the maximum number of nodes supported on a single SynqNet network. This define should be used instead of the MEIXmpMaxSynqNetBlocks definition in xmp.h. It is recommended that applications avoid programming to defines or structures in xmp.h

See Also

MEISynqNetCableHOP_COUNT

MEISynqNetCableHOP_COUNT

```
#define MEISynqNetCableHOP_COUNT (MEISynqNetMaxNODE_COUNT + 1)
```

Description

SynqNetMaxCableHOP_COUNT is the maximum number of cables for a SynqNet network. Presently, string and ring topologies are supported. The maximum number of cables is based on the maximum number of nodes, plus one return cable for ring topologies.

See Also

MEISynqNetCableList | MEISynqNetConfig

MEISynqNetNodeMaskELEMENTS

MEISynqNetNodeMaskELEMENTS

```
#define MEISynqNetNodeMaskELEMENTS (1)
typedef long MEISynqNetFailedNodeMask  [MEISynqNetNodeMaskELEMENTS];
```

Description

SynqNetNodeMaskELEMENTS defines the number of data elements in an MEISynqNetFailedNodeMask.

See Also

MEISynqNetFailedNodeMask

MEISynqNetConfig

MEISynqNetConfig

```
typedef struct MEISynqNetConfig {
    MEISynqNetRecoveryMode   recoveryMode;
    MEISynqNetCableLength    cableLength[MEISynqNetCableHOP_COUNT];
} MEISynqNetConfig;
```

Description

The **SynqNetConfig** structure contains configurations for the network's fault recovery mode and the network's cable lengths. The SynqNet configuration can be read with meiSynqNetConfigGet(…) and can be written with meiSynqNetConfigSet(…).

recoveryMode	A enumerated value representing the network's fault recovery response mode.
cableLength	An array of cable lengths. Range for cable lengths is 0 to 100 meters. This structure is provided to allow the user application to specify minimum, maximum, and nominal values to use network scheduling equations. Setting a minimum and maximum value will also enable cable length checking at network initialization time. If measured cable lengths fall outside the range defined by the minimum and maximum values, network initialization will fail with a return value of MEISynqNetMessageCABLE_LENGTH_MISMATCH. By default, the values in this structure are zero. Most applications will not need to modify these defaults. **NOTE**: The network topology must be saved before changing these values in Flash memory. These values will also be cleared when network topology is cleared using meiSynqNetFlashTopologyClear(…)

See Also

meiSynqNetConfigGet | meiSynqNetConfigSet | meiSynqNetInfo | meiSynqNetFlashConfigGet | meiSynqNetFlashConfigSet | meiSynqNetFlashTopologyClear

MEISynqNetCableStatus

MEISynqNetCableStatus

```
typedef enum MEISynqNetCableStatus {
        MEISynqNetCableStatusGOOD,
        MEISynqNetCableStatusBAD_UPSTREAM,
        MEISynqNetCableStatusBAD_DOWNSTREAM,
        MEISynqNetCableStatusBAD,
} MEISynqNetCableStatus;
```

Description

SynqNetCableStatus is an enumeration of a network connection's operating condition. Data transmission is verified in both directions. If the network hardware does not support separate upstream and downstream data path verification, it will report either GOOD or BAD.

MEISynqNetCableStatusGOOD	Network communication across the cable is working properly in both directions.
MEISynqNetCableStatusBAD_UPSTREAM	Network communication across the cable failed in the upstream direction (from node to controller).
MEISynqNetCableStatusBAD_DOWNSTREAM	Network communication across the cable failed in the downstream direction (from the controller to the node).
MEISynqNetCableStatusBAD	Network communication across the cable failed in both directions.

See Also

meiSynqNetIdleCableStatus | meiSynqNetIdleCableListGet

MEISynqNetState

MEISynqNetState

```
typedef enum MEISynqNetState {
    MEISynqNetStateINVALID,
    MEISynqNetStateDISCOVERY,
    MEISynqNetStateASYNQ,
    MEISynqNetStateSYNQ,
    MEISynqNetStateSYNQ_RECOVERING,
} MEISynqNetState;
```

Description

SynqNetState is an enumeration of the SynqNet network states. Each state shows the present operation mode for the network. Network data traffic occurs in two modes: asynchronous and synchronous.

During **asynchronous** communication, the MPI or controller sends one packet to one node and the node responds with one packet. There are no timing restrictions. Asynchronous communication is used during network initialization, reset, discovery, and node binary download.

During **synchronous** communication, the controller sends packets to the nodes and the nodes respond with packets. All data traffic is scheduled in fixed timeslots to avoid collisions. Packet data updates are cyclic and synchronized to the controller's sample rate. The network state can be read with meiSynqNetStatus(…).

MEISynqNetStateDISCOVERY	This is the initial state before the network is initialized. During this phase, the controller checks the network integrity, determines the network topology, resets the nodes, identifies, initializes, and addresses the nodes. Data packets are sent/received asynchronously.
MEISynqNetStateASYNQ	This state is used for off-line operations, like node binary download. Data packets are sent/received asynchronously.
MEISynqNetStateSYNQ	This is the normal operating state. Data packets are sent/received synchronously.

MEISynqNetStateSYNQ_RECOVERING	During this state, a network fault condition was detected and the network is being reconfigured to route data packets around the fault. After the reconfiguration is complete and the packet error rate counters have decremented to zero, the network will return to the SYNQ state.

See Also

MEISynqNetStatus | meiSynqNetStatus

MEISynqNetInfo

MEISynqNetInfo

```
typedef struct MEISynqNetInfo {
    MEINetworkType          networkType;
    long                    nodeCount;
    long                    nodeOffset;
    MEISynqNetCableLength   cableLength[MEISynqNetCableHOP_COUNT];
                               /* measured length */
} MEISynqNetInfo;
```

Description

The **SynqNetInfo** structure contains static data that is determined during network initialization. It identifies the network type, number of nodes on the network, starting number (offset) of the first node, and an rough estimate of measured cable lengths.

networkType	contains currently discovered network topology type.
nodeCount	Contains the number of nodes currently discovered on the network.
nodeOffset	Starting node number for nodes on this network. Nodes are currently numbered sequentially across all networks on a controller.
cableLength	An array of measured network cable lengths. These values are estimated values. At network discovery, where network topology has not been saved to flash, the controller will send network packets to measure each cable length and automatically fill out these values for each cable found. These values are estimated values and are the values used in the network scheduling calculations.

See Also

meiSynqNetInfo | MEISynqNetConfig

MEISynqNetPacketCfg

MEISynqNetPacketCfg

```
typedef struct MEISynqNetPacketCfg {
    MEISynqNetPacketCfgNode node[MEISynqNetMaxNODE_COUNT];
} MEISynqNetPacketCfg;
```

Description

The **SynqNetPacketCfg** structure is used as a parameter to the meiSynqNetPacketConfigGet/Set methods. It contains the network packet configuration for all nodes found on the network. Only configurable packet data is represented in this structure.

NOTE: Fixed packet fields are NOT application configurable.

node	is an array of configurable packet structures for node data. Array indices 0 through MEISynqNetInfo.nodeCount are valid, with a maximum number of motors per node being defined by MEISynqNetMaxNODE_COUNT.

See Also

meiSynqNetPacketConfigSet | meiSynqNetPacketConfigGet | MEISynqNetPacketCfgNode | MEISynqNetPacketCfgMotor | MEISynqNetPacketCfgEncoder

MEISynqNetTiming

MEISynqNetTiming

```
typedef struct MEISynqNetTiming {
    double controllerFreq;      /* kHz */
    double controllerPeriod;    /* uS  */

    long   txTime;              /*  %  */
    double calculationLimit;    /* uS  */

    double driveUpdateFreq;     /* kHz */
    double driveUpdatePeriod;   /* uS  */

    long   bandwidthUsage;      /*  %  */

    struct {
        double calculationTime; /* uS  */
        double calculationSlack;/* uS  */
        double demandLatency;   /* uS  */
        double feedbackLatency; /* uS  */

        double total;           /* uS  */
        double latencySlack;    /* uS  */
    } controlLatency;

    struct {
        double synq;            /* uS  - synq packet + spacing         */
        double demand;          /* uS  - sum demand packets + spacing  */
        double control;         /* uS  - sum control packets + spacing */

        double total;           /* uS  */
    } downstream;

    struct {
        double feedback;        /* uS  - sum feedback packets + spacing */
        double status;          /* uS  - sum status packets + spacing   */

        double total;           /* uS  */
    } upstream;
} MEISynqNetTiming;
```

Description

The **SynqNetTiming** structure contains static data that is determined during network initialization. It identifies timing statistics about the current network. Most values are just reported based on network timing calculations. The values that can be configured by the MPI are stated below as configurable.

controllerFreq	The sample rate calculation of the SynqNet controller board, in kHz. It is also the rate at which SynqNet packets are sent. The controllerFreq must be configured so that the driveUpdateFreq is an integer multiple of the controllerFreq. This value is configurable. See MPIControlConfig.
controllerPeriod	The sample period calculation of the SynqNet controller board, in uS. Derived from controllerFreq.
txTime	The scheduled time for SynqNet packets to be sent, in % (of the controllerPeriod). Defaults to 75%. Must be set to a value greater than the foreground calculation time, and less than 100%. This value is configurable. See MEIControlConfig.
calculationLimit	The maximum allowed foreground calculation time, in uS. Derived from txTime * controllerPeriod.
driveUpdateFreq	The cyclic communication rate of a drive processor on a SynqNet node, in kHz. Typically fixed to 16 kHz, but may vary depending on drive type. May be configurable on some drives. This rate often matches the drive PWM rate.
driveUpdatePeriod	The cyclic communication period of a drive processor on a SynqNet node, in uS. Derived from driveUpdateFreq.
bandwidthUsage	The amount of SynqNet bandwidth used, in %, for this SynqNet configuration. The actual packet payload configured is divided by the maximum available SynqNet bandwidth, for both upstream and downstream packets. The greater of the two is reported.
calculationTime	The foreground calculation time of the controller, in uS.
calculationSlack	The available slack time between the foreground calculation time, and the scheduled txTime, in uS.

demandLatency	The time to send SynqNet demand data downstream from controller to nodes, in uS. Does not include drive demand delays.
feedbackLatency	The time to send SynqNet feedback data upstream from nodes to controller, in uS. Rounded up to make the total SynqNet latency an integer multiple of the driveUpdatePeriod. Does not include drive feedback delays.
latencySlack	The slack time from the configured feedbackLatency (which is rounded up to an integer multiple of the driveUpdatePeriod), to the minimum possible upstream delay, in uS.
controlLatency	The overall SynqNet system control latency, in uS. Always rounded up to an integer multiple of driveUpdatePeriod. Control latency begins when position feedback is sampled on the node, includes upstream packet delays, controller foreground calculation, downstream packet delays, and ends when demands are strobed on the nodes. Note drive feedback and demand delays are NOT included. Control latency can be broken down into the four components listed below: feedbackLatency, calculationTime, calculationSlack, and demandLatency.
synq	Downstream SYNQ packet payload, in uS. Includes spacing between packets.
demand	Downstream DEMAND packet payload, in uS. Includes spacing between packets.
control	Downstream CONTROL packet payload, in uS. Includes spacing between packets.
downstream	Total downstream (controller to nodes) packet payload, in uS. Includes spacing between packets. Breaks down into the following three packet types.
feedback	Upstream FEEDBACK packet payload, in uS. Includes spacing between packets.
status	Upstream STATUS packet payload, in uS. Includes spacing between packets.
upstream	Total upstream (nodes to controller) packet payload, in uS. Includes spacing between packets. Breaks down into the following two packet types.

See Also

SynqNet Timing Values