

Compensator Objects

Introduction

A **Compensator** object manages a single compensation table. Its primary function is to provide an interface to configure both the compensating axes and the compensated axis. It also provides an interface for loading the on-controller compensation tables. The Compensator object is a host-based object that has a corresponding compensator object embedded on the controller. The embedded compensator handles the real-time issues associated with axis position compensation.

Before creating the MPI Compensator object, the corresponding embedded compensator object on the controller must be enabled. Also, before configuring the MPI Compensator object, the controller's compensation table must be allocated with a sufficient size to hold all required compensation values (or points). Both of these items can be configured using `mpiControlConfigGet/Set(...)` methods.

NOTE: Configuring the compensator table size using `mpiControlConfigSet(...)` will reallocate the controller's dynamic memory. Reallocating dynamic memory on the controller affects multiple objects and should only be done at the very beginning of your application.

For more information on determining compensation table size please see [Determining Required Compensator Table Size](#).

Methods

Create, Delete, Validate Methods

mpiCompensatorCreate	Create Compensator object
mpiCompensatorDelete	Delete Compensator object
mpiCompensatorValidate	Validate Compensator object

Configuration and Information Methods

mpiCompensatorConfigGet	Get Compensator configuration
mpiCompensatorConfigSet	Set Compensator configuration
meiCompensatorInfo	Get Compensator information
meiCompensatorTableGet	Get Compensator table
meiCompensatorTableSet	Set Compensator table

Memory Methods

[meiCompensatorMemory](#)

Set address to be used to access Compensator memory

[meiCompensatorMemoryGet](#)

Get bytes of Compensator memory and place it into application memory

[meiCompensatorMemorySet](#)

Put (set) bytes of application memory into Compensator memory

Relational Methods

[meiCompensatorControl](#)

Return handle of Control object associated with Compensator

[meiCompensatorNumber](#)

Get number of Compensator

Data Types

[MPICompensatorConfig](#)

[MPICompensatorDimension](#)

[MPICompensatorInfo](#)

[MPICompensatorInputAxis](#)

[MPICompensatorMessage](#)

[MPICompensatorRange](#)

Constants

[MPICompensatorDimensionsMAX](#)

mpiCompensatorDelete

Declaration long `mpiCompensatorDelete`([MPICompensator](#) `compensator`) ;

Required Header stdmpi.h

Description **CompensatorDelete** deletes a host Compensator object (*compensator*) and invalidates its handle.

CompensatorDelete is the equivalent of a C++ destructor.

Return Values

MPIMessageOK	if <i>CompensatorDelete</i> successfully deletes a Compensator object and invalidates its handle
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See Also [mpiCompensatorCreate](#) | [mpiCompensatorValidate](#)

mpiCompensatorValidate

Declaration long [mpiCompensatorValidate](#) ([MPICompensator](#) *compensator*) ;

Required Header stdmpi.h

Description **CompensatorValidate** CompensatorValidate validates the Compensator object (*compensator*) and its handle. Always call mpiCompensatorValidate after creating a new Compensator object.

Return Values

MPIMessageOK	if Compensator is a handle to a valid object.
MPICompensatorMessageCOMPENSATOR_INVALID	If the <i>number</i> used in mpiCompensatorCreate() was not a valid number. Valid numbers range from 0 to MPIControlMAX_COMPENSATORS
MPICompensatorMessageNOT_ENABLED	If the corresponding controller compensation object number is valid but is disabled on the controller.

See Also [mpiCompensatorCreate](#) | [mpiCompensatorDelete](#)

mpiCompensatorConfigGet

Declaration

```
long mpiCompensatorConfigGet(MPICompensator      compensator ,
                             MPICompensatorConfig *config ,
                             void                *external ) ;
```

Required Header `stdmpi.h`

Description

CompensatorConfigGet gets the configuration of a Compensator object (*compensator*) and puts (writes) it in the structure pointed to by *config*, and also writes it into the implementation-specific structure pointed to by *external* (if *external* is not NULL).

The configuration information in *external* is intended for future use and is not currently used. Set this value to NULL.

Return Values

MPIMessageOK	if <i>CompensatorConfigGet</i> successfully gets the configuration of a Compensator object and writes it into the structure(s).
MPIMessagePARAM_INVALID	If <i>*config</i> parameter is NULL, or if <i>*external</i> parameter is NOT NULL.

See Also [mpiCompensatorConfigSet](#) | [MEICompensatorConfig](#)

mpiCompensatorConfigSet

Declaration

```
long mpiCompensatorConfigSet(MPIStruct MPICompensator      compensator,
                             MPICompensatorConfig *config,
                             void *external);
```

Required Header stdmpi.h

Description

CompensatorConfigSet sets (writes) the configuration of a Compensator object (*compensator*) using data from the structure pointed to by *config*, and also using data from the implementation-specific structure pointed to by *external* (if *external* is not NULL).

The configuration information in *external* is in addition to the configuration information in *config*, i.e. the configuration information in *config* and in *external* is not the same information.

NOTE: *config* or *external* can be NULL (but both cannot be NULL).

XMP Only

external either points to a structure of type **MEICompensatorConfig{}** or is NULL.

Return Values

MPIMessageOK	if <i>CompensatorConfigSet</i> successfully writes the configuration of a Compensator object using data from the structure(s)
MPIMessagePARAM_INVALID	If <i>*config</i> parameter is NULL, or if <i>*external</i> parameter is NOT NULL
MPIMessageARG_INVALID	The axisOutNumber or any of the inputAxis[n].axisNumbers correspond to invalid Axis objects on the controller. See MPICompensatorConfig .
MPICompensatorMessageDIMENSION_NOT_SUPPORTED	dimensionCount is out of range. See MPICompensatorConfig .

MPICompensatorMessage AXIS_NOT_ENABLED	The axisOutNumber or any of the inputAxis[n].axisNumbers correspond to disabled Axis objects on the controller. See MPICompensatorConfig .
MPICompensatorMessage POSITION_DELTA_INVALID	The <i>positionDelta</i> argument is either out of range or not a multiple of the range. See MPICompensatorConfig .
MPICompensatorMessage TABLE_SIZE_ERROR	The host compensation table will not fit within the controller's configured compensation table. See Determining Required Compensator Table Size .

See Also [mpiCompensatorConfigGet](#) | [MEICompensatorConfig](#)

mpiCompensatorInfo

Declaration

```
long mpiCompensatorInfo(MPICompensator compensator,  
                        MPICompensatorInfo *info);
```

Required Header

stdmpi.h

Description

[CompensatorInfo](#) reads the static information about the compensator object, and writes it into the structure pointed to by *info*.

compensator	a handle to the Compensator object.
*info	a pointer to a compensator information structure.

Return Values

MPIMessageOK	if <i>CompensatorInfo</i> successfully writes the Compensator object information into the <i>info</i> structure.
MPICompensatorMessageNOT_CONFIGURED	MPI Compensator object must be configured before calling mpiCompensatorTableGet/Set or mpiCompensatorInfo .

See Also

[MPICompensatorInfo](#) | [MPIControlConfig](#) | [mpiCompensatorTableGet](#) | [mpiCompensatorTableSet](#) | [mpiCompensatorInfo](#)

mpiCompensatorTableGet

Declaration

```
long  mpiCompensatorTableGet ( MPICompensator  compensator ,
                               long             *table ) ;
```

Required Header stdmpi.h

Description **CompensatorTableGet** reads the NxM Compensator table stored on the controller whose dimensions are defined by the values in the MPICompensatorConfig structure. These values are written into the location specified by **table*.

NOTE: The array pointed to **table* must have enough memory allocated to hold the entire size of the configured compensation table.

Return Values

MPIMessageOK	
MPICompensatorMessageNOT_CONFIGURED	MPI Compensator object must be configured before calling mpiCompensatorTableGet/Set or mpiCompensatorInfo.
MPIMessagePARAM_INVALID	If <i>*table</i> is NULL.

See Also [mpiCompensatorTableSet](#) | [MPICompensatorConfig](#)

mpiCompensatorTableSet

Declaration

```
long  mpiCompensatorTableSet (MPICompensator  compensator ,
                              long            *table) ;
```

Required Header stdmpi.h

Description **CompensatorTableSet** writes the values stored in the location specified by **table* to the Compensator table stored on the controller.

NOTE: The array pointed to **table* must have a size large enough to fill the configured compensation table size (as defined by the [MPICompensatorConfig](#) structure) or memory access violations may occur.

Return Values

MPIMessageOK	
MPICompensatorMessageNOT_CONFIGURED	MPI Compensator object must be configured before calling mpiCompensatorTableGet/Set or mpiCompensatorInfo.
MPIMessagePARAM_INVALID	If <i>*table</i> is NULL.

See Also [mpiCompensatorTableGet](#) | [MPICompensatorConfig](#)

mpiCompensatorMemory

Declaration

```
long  mpiCompensatorMemory(MPICompensator  compensator,
                             void           **memory);
```

Required Header `stdmpi.h`

Description [CompensatorMemory](#) sets (writes) an address (used to access a Compensator object's memory) to the contents of *memory*.

Return Values

MPIMessageOK

if *CompensatorMemory* successfully writes the Compensator's address to the contents of *memory*.

See Also [mpiCompensatorMemoryGet](#) | [mpiCompensatorMemorySet](#)

mpiCompensatorMemoryGet

Declaration

```
long  mpiCompensatorMemoryGet (MPICompensator  compensator ,
                                void             *dst ,
                                void             *src ,
                                long             count ) ;
```

Required Header `stdmpi.h`

Description **CompensatorMemoryGet** copies *count* bytes of a Compensator's (*compensator*) memory (starting at address *src*) to application memory (starting at address *dst*).

Return Values

MPIMessageOK

if *CompensatorMemoryGet* successfully copies data from Compensator memory to application memory.

See Also [mpiCompensatorMemorySet](#) | [mpiCompensatorMemory](#)

mpiCompensatorMemorySet

Declaration

```
long  mpiCompensatorMemorySet (MPICompensator  compensator ,
                                void            *dst ,
                                void            *src ,
                                long           count ) ;
```

Required Header `stdmpi.h`

Description **CompensatorMemorySet** copies *count* bytes of application memory (starting at address *src*) to a Compensator's (*compensator*) memory (starting at address *dst*).

Return Values

MPIMessageOK

if *CompensatorMemorySet* successfully copies data from application memory to Compensator memory.

See Also [mpiCompensatorMemoryGet](#) | [mpiCompensatorMemory](#)

mpiCompensatorControl

Declaration

```
MPIControl mpiCompensatorControl(MPICompensator compensator);
```

Required Header `stdmpi.h`

Description **CompensatorControl** returns a handle to the Control object with which the compensator is associated.

compensator	a handle to the Compensator object
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Return Values

MPIControl	handle to a Control object
MPIHandleVOID	if <i>compensator</i> is invalid

See Also [mpiCompensatorCreate](#) | [mpiControlCreate](#)

mpiCompensatorNumber

Declaration

```
long mpiCompensatorNumber (MPICompensator compensator,  
long *number ) ;
```

Required Header `stdmpi.h`

Description [CompensatorNumber](#) writes the index of a compensation object (object on the motion controller that the Compensator object is associated with) to the contents of *number*.

Return Values

MPIMessageOK	if <i>CompensatorNumber</i> successfully writes the index of a compensation object to the contents of <i>number</i> .
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See Also [mpiCompensatorCreate](#)

MPICompensatorConfig

MPICompensatorConfig

```
typedef struct MPICompensatorConfig {
    long                dimensionCount ,
    MPICompensatorInputAxis inputAxis[MPICompensatorDimensionMAX] ,
    long                outputAxisNumber ,
} MPICompensatorConfig;
```

Description

dimensionCount	The input dimension count of the compensation table. Valid values are from zero (0) to MPICompensatorDimensionsMAX . A value of zero (0) effectively disables the compensation object
inputAxis	The substructure used to configure each input dimension of the Compensator object.
outputAxisNumber	This specifies the axis number of the Axis to be compensated by the Compensator object. This number must correspond to a valid (existing) and enabled Axis on the controller.

See Also [MPIControlConfig](#) | [mpiCompensatorConfigGet](#) | [mpiCompensatorConfigSet](#) | [MPICompensatorDimension](#) | [MPICompensatorDimensionsMAX](#)

MPICompensatorDimension

MPICompensatorDimension

```
typedef struct MPICompensatorDimension {  
    MPICompensatorDimensionX,  
    MPICompensatorDimensionY,  
} MPICompensatorDimension;
```

Description **CompensatorDimension** an enumeration of valid Compensator dimensions.

MPICompensatorDimensionX	First Compensating Dimension
MPICompensatorDimensionY	Second Compensating Dimension

See Also [MPICompensatorConfig](#) | [MPICompensatorInfo](#)

MPICompensatorInfo

MPICompensatorInfo

```
typedef struct MPICompensatorInfo {  
    long    tableDimensions[MPICompensatorDimensionMAX],  
    long    tableSizeBytes,  
} MPICompensatorInfo;
```

Description

tableDimensions	The dimensions along each axis of the table. This value is affected by the values set in the MPICompensatorConfig structure.
tableSizeBytes	The size (in Byte) required to store the entire compensation table in a host resident structure or array. This value is affected by the values set in the MPICompensatorConfig structure. This is NOT the amount of memory allocated on the controller by setting the MPIControlConfig.compensatorPointCount value.

See Also [MPICompensatorConfig](#) | [MPIControlConfig](#) | [MPICompensatorDimension](#) | [MPICompensatorDimensionMAX](#)

MPICompensatorInputAxis

MPICompensatorInputAxis

```
typedef struct MPICompensatorInputAxis {
    long                axisNumber,
    MPICompensatorRange range,
    long                positionDelta,
} MPICompensatorInputAxis;
```

Description

axisNumber	This specifies the axis number of the compensating Axis object. The position from this Axis will be used to index a single dimension of the compensation table. This number must correspond to a valid (existing) and enabled Axis on the controller.
range	Used to configure the feedback positions along the compensation axis where compensation will start and end.
positionDelete	Spacing between compensation positions on the compensating axis. NOTE: This value must be an exact multiple of the range (i.e. the difference between range.positionMax – range.positionMin)

See Also [MPICompensatorConfig](#) | [mpiCompensatorConfigGet](#) | [mpiCompensatorConfigSet](#)

MPICompensatorMessage

MPICompensatorMessage

```
typedef enum {
    MPICompensatorMessageCOMPENSATOR_INVALID,
    MPICompensatorMessageNOT_CONFIGURED,
    MPICompensatorMessageNOT_ENABLED,
    MPICompensatorMessageAXIS_NOT_ENABLED,
    MPICompensatorMessageTABLE_SIZE_ERROR,
    MPICompensatorMessagePOSITION_DELTA_INVALID,
    MPICompensatorMessageDIMENSION_NOT_SUPPORTED,
} MPICompensatorMessage;
```

Description

MPICompensatorMessageCOMPENSATOR_INVALID

If the number used to in `mpiCompensatorCreate(...)` was not a valid number. Valid numbers range from 0 to `MPIControlMAX_COMPENSATORS`.

MPICompensatorMessageNOT_CONFIGURED

MPI Compensator object must be configured before calling `mpiCompensatorTableGet/Set` or `mpiCompensatorInfo`.

MPICompensatorMessageNOT_ENABLED

If the corresponding controller compensation object number is valid, but is disabled on the controller.

MPICompensatorMessageAXIS_NOT_ENABLED

The `axisOutNumber` or any of the `inputAxis[n].axisNumbers` correspond to disabled Axis objects on the controller. See [MPICompensatorConfig{}](#).

MPICompensatorMessageTABLE_SIZE_ERROR

The host compensation table will not fit within the controller's configured compensation table. See [Determining Required Compensation Table Size](#).

MPICompensatorMessagePOSITION_DELTA_INVALID

The `positionDelta` argument is either out of range or is not a multiple of the range. See [MPICompensatorConfig{}](#).

MPICompensatorMessageDIMENSION_NOT_SUPPORTED

`dimensionCount` is out of range. See [MPICompensatorConfig{}](#) for more information.

MPICompensatorRange

MPICompensatorRange

```
typedef struct MPICompensatorRange {  
    long    positionMin,  
    long    positionMax,  
} MPICompensatorRange;
```

Description

positionMin	The minimum feedback position (counts) along the compensation axis where compensation will occur.
positionMax	The maximum feedback position (counts) along the compensation axis where compensation will occur.

See Also [MPICompensatorConfig](#) | [mpiCompensatorConfigGet](#) | [mpiCompensatorConfigSet](#)

MPIControlDimensionsMAX

Declaration

```
#define MPIControlDimensionsMAX (MPICompensatorDimensionLAST)
```

Required Header stdmpi.h

Description **MPIControlDimensionsMAX** defines the maximum number of dimensions supported by the Compensator object's compensation tables.

See Also [MPICompensatorDimension](#) | [MPICompensatorInfo](#) | [MPICompensatorConfig](#)

Determining Required Compensator Table Size

The compensator table size is dependent on the number of dimensions (1D or 2D), the position range, and the resolution (or granularity) of the compensation points. The compensator uses linear interpolation to calculate the compensation values between each distinct compensation point.

For each compensation axis there are three position values: Min, Max, and Delta. The compensating range for an axis is specified by the Min and Max positions along the axis. The range (Max – Min) divided by Delta, determines the number of required points for the compensator. You can calculate the number of required compensator points by using the following equations:

1D Compensation: $\text{Points} = (\text{positionMax} - \text{positionMin}) / \text{positionDelta}$

2D Compensation: $\text{Points} = \text{PointsX} * \text{PointsY}$

NOTE: Delta must be an exact multiple of the difference between Min and Max.

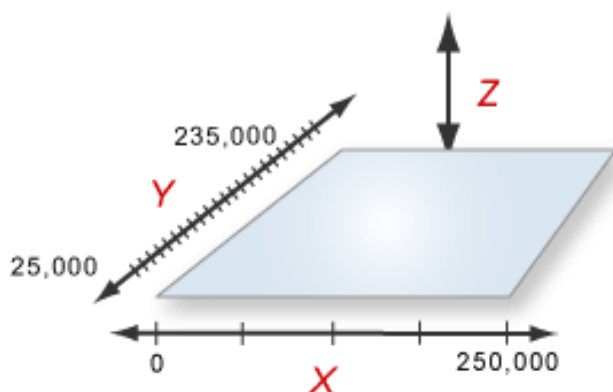
Example: (taken from comp.c sample application)

To compensate a Z (vertical) axis for X-Y surface irregularities, first define the X-Y area to be compensated (Xmin to Xmax, Ymin to Ymax). Then define the spacing of the measuring points (delta) for the X and Y axes to determine the compensation table size.

For the X-Y table diagram below we have:

Xmin = 0, Xmax = 250000, Xdelta = 50000

Ymin = 25000, Ymax = 235000, Ydelta = 10000



For this table our X & Y dimensions are:

$X_DIM = (250000 - 0) / 50000 = 5$

$$Y_DIM = (235000-25000)/10000 = 21$$

which requires a table point count of:

$$Points = X_DIM * Y_DIM = 105$$

With this information we can now configure the size of our compensation table on the controller using `MPIControlConfig.compensatorPointCount = 105;`